

**1999 3.0L (L81) V-car Catera**  
**4L30-E TRANSMISSION DIAGNOSTIC PARAMETERS**

**99c30R\_V\_aT.DOC**

P code	Fault name	DTC type	Failure enabling conditions	Failure major conditions	Monitoring time length (ms) (1 MLT = 15ms)
<b>P 0560</b>	System Voltage	<b>B</b>	no hysteresis range (9.5 V - 9 V)	Ubatt <= KVLO1 (9V)	149+1 MLT = 2.25s
<b>P 0560</b>	System Voltage	<b>B</b>	no hysteresis range (15.5V - 16V)	Ubatt >= KVLHI1 (16V)	149+1 MLT = 2.25s
<b>P 0601</b>	TCM Memory- ROM	<b>B</b>	none	calculated checksum different from EEPROM checksum	1318+1 MLT (40s) & (20 times faster during initialization : 2s)
<b>P 0602</b>	TCM Not Programmed	<b>B</b>	1 time after power on reset	a wrong data or a wrong checksum is detected in the transmission configuration range of EEPROM	Immediate
<b>P 0602</b>	TCM Not Programmed	<b>B</b>	Ignition off (at that time the EEPROM is updated).	read bytes not equal to written bytes	Immediate
<b>P 0705</b>	Transmission Range Switch Circuit	<b>B</b>	none	Switch decodes electrical failure (flags Z+E)	(MLT+1)x KMODMLF (9+1)x1,995s = 19.95s
<b>P 0705</b>	Transmission Range Switch Circuit	<b>B</b>	none	Switch decodes undefined state (flag Z)	(MLT+1)x KMODMLF (9+1)x1,995s = 19.95s
<b>P 0722</b>	Output Speed Sensor Circuit-Low Input	<b>B</b>	- position not equal to P, R, N or Z - ES > KVSHLFNE (3008rpm)	Output speed = 0	255+1 MLT = 3.84s
<b>P 0725</b>	Engine Speed Input Circuit- Low Input	<b>B</b>	- position not equal to P, R, N or Z - Throttle > KNEMLFTH (12%) - OS > KNEMLFVS (1024rpm)	N_MOT <= 112rpm	255+1 MLT = 3.84s
<b>P 0727</b>	Engine speed Input Circuit	<b>B</b>	none	- CAN information VALID_ESPEED = 1 or 2 or 3	66+1 MLT = 1s
<b>P 0730</b>	Incorrect Gear Ratio	<b>B</b>	position not equal to P, R, N or Z - No Safety Mode - only in main loop - static conditions - enable conditions met or set for code P0757, Fail case 1 1. ES > ES_LIM (3488rpm) 2. 3rd gear, ES > OS > OS_LIM (2976rpm)	1. abs(OS - N_Absoll) > SCHLUPF characteristic line f(gear) : Absolute slippage > Gear 1 : SCHLUPF[0] (352rpm) Gear 2 : SCHLUPF[1] (576rpm) Gear 3 : SCHLUPF[2] (896rpm) Gear 4 : SCHLUPF[3] (1216rpm) 2. ES < OS - SCHLUPF2 (992rpm)	225+1 MLT = 3.39s
<b>P 0742</b>	TCC System - Stuck On	<b>B</b>	- TCC mode = OFF - GEAR >> FIRST - Eng. running status set - HCCU_FP (18.18%) < Throttle < HCCO_FP (100%) - Selector = D - MCCU_MM (50Nm) < Engine torque < Mcco_MM (200Nm) - NCCU_ES (1000rpm) < ES < NCCO_ES (3488rpm) - NCCU_VS (25Kph) < Veh. Spd < NCCO_VS (120Kph) - No Throttle, OS, ES and TCC codes	NCCU_FSS (-20rpm ) < SLIP < NCC_FSS (64rpm ) for a time >= TCC_FSS (3s.)  If conditions are met, increment "Fail counter".  To fail "Fail counter" >= 2	depends on fail detection (minimum 6s.)
<b>P 0743</b>	TCC Enable Solenoid Circuit - short to ground	<b>B</b>	- TCC solenoid commanded off - FET driver closed	- (TCC) Feedback voltage < UCG_KM (2,45V)	11+1 MLT = 180ms

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<b>P 0743</b>	TCC Enable Solenoid Circuit - open	<b>B</b>	- TCC solenoid commanded off - FET driver closed	- UCG_KM (2,45V) <= (TCC) Feedback voltage < UCG_UBR (3,53V)	11+1 MLT = 180ms
<b>P 0743</b>	TCC Enable Solenoid Circuit - short to battery	<b>B</b>	- TCC solenoid commanded on - FET driver closed	- (TCC) Feedback voltage > UCG_KP (4,02V)	11+1 MLT = 180ms
<b>P 0748</b>	Pressure Control Solenoid Circuit Electrical	<b>B</b>	- FET driver closed - Force motor on. - IWERT > (DR_PB=f(TEMPG,UBATT))	- No falling edge on feedback line during 2ms - Feedback Voltage is low	<u>Initialization :</u> 500ms <u>Main loop :</u> 35+1 MLT = 540ms
<b>P 0748</b>	Pressure Control Solenoid Circuit Electrical	<b>B</b>	- FET driver closed - Force motor on.	- No falling edge on feedback line during 2ms - Feedback Voltage is high	<u>Initialization :</u> 500ms <u>Main loop :</u> 35+1 MLT = 540ms
<b>P0751</b>	Shift solenoid 1-2/3-4 stuck off (1-1-4-4)	<b>B</b>	<ul style="list-style-type: none"> <li>- Range = D4</li> <li>- No 705, 722, 753, 758, 1600, 1625, 1743, 1890 codes set.</li> </ul> <u>Fail case 1 :</u> <ul style="list-style-type: none"> <li>- Commanded gear = 2 for a time &gt;= TSP_F(CG[2] (0,7s.)</li> <li>- Throttle (pedal) &gt;= HSPS_FTP[2] (30,8%)</li> <li>- NSPU_FES[2] (3104rpm) &lt;= ES &lt;= NSPO_FES[2] (3904rpm)</li> <li>- OS &gt;= NSPS_FOS[2] (992rpm)</li> <li>- Torque &gt;= MSPS_FMM[2] (50Nm)</li> <li>(if all conditions resets Pass case 1)</li> </ul> <u>Fail case 2 :</u> <ul style="list-style-type: none"> <li>- Commanded gear = 3 for a time &gt;= TSP_F(CG[4] (0,7s.)</li> <li>- Throttle (pedal) &gt;= HSPS_FTP[4] (24.9%)</li> <li>- NSPU_FES[4] (1216rpm) &lt;= ES &lt;= NSPO_FES[4] (2016rpm)</li> <li>- OS &gt;= NSPS_FOS[4] (2016rpm)</li> <li>- Torque &gt;= MSPS_FMM[4] (50Nm)</li> <li>(if all conditions met, resets Pass case 2)</li> <li>- TCC is commanded on</li> </ul>	<ul style="list-style-type: none"> <li>1) - Fail case 1           <ul style="list-style-type: none"> <li>- NSPU_FSS[2] (1400rpm) &lt;= TCC slip &lt;= NSPO_FSS[2] (2000rpm) for a time &gt;= TSP_FC[2] (0,9s.)</li> </ul> </li> <li>2) - Fail case 2           <ul style="list-style-type: none"> <li>- NSPU_FSS[4] (-1000rpm) &lt;= TCC slip &lt;= NSPO_FSS[4] (-1000rpm) for a time &gt;= TSP_FC[4] (3s.)</li> </ul> </li> </ul> <p>If case 1) and 2) are met, increment Fail counter.</p> <p>Fail counter &gt;= 2</p>	Depends on Commanded Gear

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<b>P0752</b>	Shift solenoid 1-2/3-4 stuck on (2-2-3-3)	<b>B</b>	<ul style="list-style-type: none"> <li>- Range = D4</li> <li>- No 705, 722, 753, 758, 1600, 1625, 1743, 1890 codes set.</li> </ul> <p><u>Fail case 1 :</u></p> <ul style="list-style-type: none"> <li>- Commanded gear = 1 for a time <math>\geq</math> TSP_F_CG[0] (1,5s.)</li> <li>- Throttle (pedal) <math>\geq</math> HSPS_FTP[0] (41,1%)</li> <li>- NSPU_FES[0] (2400rpm) <math>\leq</math> ES <math>\leq</math> NSPO_FES[0] (3008rpm)</li> <li>- OS <math>\geq</math> NSPS_FOS[0] (704rpm)</li> <li>- Torque <math>\geq</math> MSPS_FMM[0] (50Nm) (if all conditions resets Pass case 1)</li> </ul> <p><u>Fail case 2 :</u></p> <ul style="list-style-type: none"> <li>- Commanded gear = 4 for a time <math>\geq</math> TSP_F_CG[6] (0,5s.)</li> <li>- Throttle (pedal) <math>\geq</math> HSPS_FTP[6] (15%)</li> <li>- NSPU_FES[6] (1696rpm) <math>\leq</math> ES <math>\leq</math> NSPO_FES[6] (4992rpm)</li> <li>- OS <math>\geq</math> NSPS_FOS[6] (1696rpm)</li> <li>- Torque <math>\geq</math> MSPS_FMM[6] (50Nm) (if all conditions met, resets Pass case 2)</li> <li>- TCC is commanded on</li> </ul>	<ul style="list-style-type: none"> <li>1) - Fail case 1 <ul style="list-style-type: none"> <li>- NSPU_FSS[0] (-711rpm) <math>\leq</math> TCC slip <math>\leq</math> NSPO_FSS[0] (350rpm) for a time <math>\geq</math> TSP_FC[0] (0,6s.)</li> </ul> </li> <li>2) - Fail case 2 <ul style="list-style-type: none"> <li>- NSPU_FSS[6] (666rpm) <math>\leq</math> TCC slip <math>\leq</math> NSPO_FSS[6] (1000rpm) for a time <math>\geq</math> TSP_FC[6] (5s.)</li> </ul> </li> </ul> <p>If case 1) and 2) are met, increment Fail counter.</p> <p>Fail counter <math>\geq</math> 2</p>	Depends on Commanded Gear
<b>P 0753</b>	Shift solenoid 1-2/3-4 circuit - short to ground	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 1-2/3-4 commanded off</li> <li>- FET driver closed</li> </ul>	- (1-2/3-4) Feedback voltage < UCG_KM (2,45V)	11+1 MLT = 180ms
<b>P 0753</b>	Shift solenoid 1-2/3-4 circuit - open	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 1-2/3-4 commanded off</li> <li>- FET driver closed</li> </ul>	- UCG_KM (2,45V) $\leq$ (1-2/3-4) Feedback voltage < UCG_UBR (3,53V)	11+1 MLT = 180ms
<b>P 0753</b>	Shift solenoid 1-2/3-4 circuit - short to battery	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 1-2/3-4 commanded on</li> <li>- FET driver closed</li> </ul>	- (1-2/3-4) Feedback voltage > UCG_KP (4,02V)	11+1 MLT = 180ms
<b>P0756</b>	Shift solenoid 2-3 stuck off (4-3-3-4)	<b>B</b>	<ul style="list-style-type: none"> <li>- Range = D4</li> <li>- No 705, 722, 753, 758, 1600, 1625, 1743, 1890 codes set.</li> </ul> <p><u>Fail case 1 :</u></p> <ul style="list-style-type: none"> <li>- Commanded gear = 1 for a time <math>\geq</math> TSP_F_CG[1] (1,5s.)</li> <li>- Throttle (pedal) <math>\geq</math> HSPS_FTP[1] (41,1%)</li> <li>- NSPU_FES[1] (2400rpm) <math>\leq</math> ES <math>\leq</math> NSPO_FES[1] (3008rpm)</li> </ul>	<ul style="list-style-type: none"> <li>1) - Fail case 1 <ul style="list-style-type: none"> <li>- NSPU_FSS[1] (-3000rpm) <math>\leq</math> TCC slip <math>\leq</math> NSPO_FSS[1] (100rpm) for a time <math>\geq</math> TSP_FC[1] (1,5s.)</li> </ul> </li> <li>2) - Fail case 2 <ul style="list-style-type: none"> <li>- NSPU_FSS[3] (-500rpm) <math>\leq</math> TCC slip <math>\leq</math> NSPO_FSS[3] (400rpm) for a time <math>\geq</math> TSP_FC[3] (1,5s.)</li> </ul> </li> </ul>	Depends on Commanded Gear

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			<ul style="list-style-type: none"> <li>- OS &gt;= NSPS_FOS[1] (704rpm)</li> <li>- Torque &gt;= MSPS_FMM[1] (50Nm)</li> <li>(if all conditions resets Pass case 1)</li>   <u>Fail case 2 :</u> <li>- Commanded gear = 2 for a time &gt;= TSP_F(CG[3] (0,7s.)</li> <li>- Throttle (pedal) &gt;= HSPS_FTP[3] (41.8%)</li> <li>- NSPU_FES[3] (2592rpm) &lt;= ES &lt;= NSPO_FES[3] (3008rpm)</li> <li>- OS &gt;= NSPS_FOS[3] (1408rpm)</li> <li>- Torque &gt;= MSPS_FMM[3] (50Nm)</li> <li>(if all conditions met, resets Pass case 2)</li> </ul>	If case 1) and 2) are met, increment Fail counter.  Fail counter >= 2	
<b>P0757</b>	Shift solenoid 2-3 stuck on (1-2-2-1)	<b>B</b>	<ul style="list-style-type: none"> <li>- Range = D4</li> <li>- No 705, 722, 753, 758, 1600, 1625, 1743, 1890 codes set.</li>   <u>Fail case 1 :</u> <li>- Commanded gear = 3 for a time &gt;= TSP_F(CG[5] (0,7s.)</li> <li>- Throttle (pedal) &gt;= HSPS_FTP[5] (26,4%)</li> <li>- NSPU_FES[5] (3104rpm) &lt;= ES &lt;= NSPO_FES[5] (4192rpm)</li>   <li>- OS &gt;= NSPS_FOS[5] (1088rpm)</li> <li>- Torque &gt;= MSPS_FMM[5] (50Nm)</li> <li>(if all conditions resets Pass case 1)</li>   <u>Fail case 2 :</u> <li>- Commanded gear = 4 for a time &gt;= TSP_F(CG[7] (0,5s.)</li> <li>- Throttle (pedal) &gt;= HSPS_FTP[7] (13,8%)</li> <li>- NSPU_FES[7] (3008rpm) &lt;= ES &lt;= NSPO_FES[7] (6016rpm)</li> <li>- OS &gt;= NSPS_FOS[7] (1216rpm)</li> <li>- Torque &gt;= MSPS_FMM[7] (0Nm)</li> <li>(if all conditions met, resets Pass case 2)</li> </ul>	<ul style="list-style-type: none"> <li>1) - Fail case 1           <ul style="list-style-type: none"> <li>- NSPU_FSS[5] (1200rpm) &lt;= TCC slip &lt;= NSPO_FSS[5] (1800rpm) for a time &gt;= TSP_FC[5] (3s.)</li> </ul> </li>   <li>2) - Fail case 2           <ul style="list-style-type: none"> <li>- NSPU_FSS[7] (2000rpm) &lt;= TCC slip &lt;= NSPO_FSS[7] (6000rpm) for a time &gt;= TSP_FC[7] (1,3s.)</li> </ul> </li> </ul> If case 1) and 2) are met, increment Fail counter.  Fail counter >= 1	Depends on Commanded Gear
<b>P 0758</b>	Shift solenoid 2-3 circuit - short to ground	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 2-3 commanded off</li> <li>- FET driver closed</li> </ul>	- (2-3) Feedback voltage < UCG_KM (2,45V)	11+1 MLT = 180ms
<b>P 0758</b>	Shift solenoid 2-3 circuit - open	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 2-3 commanded off</li> <li>- FET driver closed</li> </ul>	- UCG_KM (2,45V) <= (2-3) Feedback voltage < UCG_UBR (3,53V)	11+1 MLT = 180ms
<b>P 0758</b>	Shift solenoid 2-3 circuit - short to battery	<b>B</b>	<ul style="list-style-type: none"> <li>- Shift solenoid 2-3 commanded on</li> <li>- FET driver closed</li> </ul>	- (2-3) Feedback voltage > UCG_KP (4,02V)	11+1 MLT = 180ms

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<b>P 1600</b>	Power control relay watchdog failure	<b>B</b>	- Only initialization - FET driver open (all outputs OFF) - UBATT > UBAT_LIM - Watchdog not released	PCR closes although no Watchdog pulses are present	Immediate
<b>P 1621</b>	TCM Long Term Memory Performance	<b>B</b>	1 time after power on reset	no EEPROM acknowledge to the TCM at first read cycle	Immediate
<b>P 1625</b>	TCM System Reset	<b>B</b>	Initialization	high output although PCR off by software and all solenoids off	Immediate
<b>P 1625</b>	TCM System Reset	<b>B</b>	Initialization	high output although Force Motor released	Immediate
<b>P 1800</b>	TCM Power Relay Output Control Circuit	<b>B</b>	No codes short to ground or open P0753, P0758, P1850, P0743	Solenoid supply is disconnected.	7+1 MLT = 120ms
<b>P 1850</b>	Band Apply Solenoid Circuit - short to ground	<b>B</b>	- Shift solenoid band commanded off - FET driver closed	- (Band) Feedback voltage < UCG_KM (2,45V)	11+1 MLT = 180ms
<b>P 1850</b>	Band Apply Solenoid Circuit - open	<b>B</b>	- Shift solenoid band commanded off - FET driver closed	- UCG_KM (2,45V) <= (Band) Feedback voltage < UCG_UBR (3,53V)	11+1 MLT = 180ms
<b>P 1850</b>	Band Apply Solenoid Circuit - short to battery	<b>B</b>	- Shift solenoid band commanded on - FET driver closed	- (Band) Feedback voltage > UCG_KP (4,02V)	11+1 MLT = 180ms
<b>P 1870</b>	Trans. component slipping	<b>B</b>	- position not equal to P, R, N or Z - No Safety Mode - TCC commanded on - only in main loop - static conditions - No P0730 code - enable conditions met or set for codes : P0751, Fail Case 1 & FC2 P0752, FC1 & FC2 P0757, FC1 & FC2	Absolute slippage (Engine speed - calculated turbine speed) > NDIS_WKZU (288rpm)	255+1 MLT = 3.825s
<b>P 1890</b>	Throttle Position Signal	<b>B</b>	none	CAN throttle information VALID_ACCEL_POS = 1	66+1 MLT = 1s
<b>P 1890</b>	Throttle angle (CAN)	<b>B</b>	none	CAN throttle information VALID_ACT_THROTTLE_ANGLE = 1	66+1 MLT = 1s
<b>U 2100</b>	CAN bus off	<b>B</b>	none	CAN driver signals bus off	66+1 MLT = 1s
<b>U 2104</b>	CAN bus reset counter overrun	<b>B</b>	none	NWM counter ZCN_DLL >= 40h	66+1 MLT = 1s
<b>P 2105</b>	CAN Bus Error ECM	<b>B</b>	none	No CAN messages from ECU	66+1 MLT = 1s