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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No
					Ì MIL)

System Voltage Low	P0562		Ignition voltage < 8.68 V Ignition ON for 1000 msec	Input speed > 800 RPM Ignition ON	1.0 sec
			0	Not in Emergency mode	FATKO
			Count = 20 @ 1.0 sec	No faults: P0717	Type A
System Voltage	P0563		Ignition voltage > 18.0 V	Input speed > 800 RPM	1.0 sec
High			Ignition ON for 1000 msec	Ignition ON	FATKO
				Not in Emergency mode	FATKO
			Count = 20 @ 1.0 sec	No faults: P0717	Туре А
Checksum Error	P0601	Calculated checksum differs from actual			2 counts
		checksum in ROM	Count = 2		
					FATKO
					Туре А
RAM Read/Write Error	P0604	Error in accessing Random Access Memory			2 counts
LIIOI		Memory			FATKO
					Туре А
Gear Selector	P0705	Failure combination of A, B, C, and PA	Count = 5 @ 1.0 sec		Illegal state ≥ 1.0
Fault		signals (see below)	_		sec
					FATKO
					Type A

Failure Modes for Selector Position Switch

Α	В	С	PA
Х	Х	Х	Х
Х	Х	Х	0
0	Х	Х	Х
Х	Х	0	Х
0	0	0	Х
Х	0	Х	Х

X = OFF O = ON

Emergency Mode $1 = 5^{\text{th}}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range

 $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 1 $EM8 = 5^{th}$ gear in D: 4th in L range

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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No MIL)
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Transmission Temperature Sensor Circuit: Low Input P0712 Detects A/D < 10 Count = 30 @ 10.0 sec Not in Emergency mode DS_Active = TRUE 10.0 sec. DS_Active = TRUE Transmission Temperature Sensor Circuit: High Input P0713 Detects A/D > 1000 Count = 12 @ 1.0 sec No Engine Coolant codes DS_Active = TRUE 1000 msec Continuou Sensor Circuit: High Input P0717 Detects no Input Speed sensor pulses while detecting pulses from Output Speed sensor Circuit: No Signal Detects no Input Speed sensor pulses while detecting pulses from Output Speed sensor Count = 500 FAIL CASE 1 Range = D, I, or L Output speed 'expected gear ratio > 600 RPM IF FAIL CASE 1 NA FAIL CASE 2 FAIL CASE 2 Input Speed Sensor Count = 300 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 3 FAIL CASE 4 FAIL CASE 2 <th>Transmission Temperature Stuck</th> <th>P0711</th> <th>Detects a Transmission Temperature which remains constant for period of time in which a measurable change is expected</th> <th>Highest temperature = Oil temperature at initialization time \pm 5° C.</th> <th>Oil temperature at initialization < 0° C. 10 < A/D of Oil temp sensor < 1000 Range = D, I, L, R DS_Active = TRUE RANGE = Q_NORMAL Not in Emergency mode</th> <th>900 sec Continuous FATKO Type A</th>	Transmission Temperature Stuck	P0711	Detects a Transmission Temperature which remains constant for period of time in which a measurable change is expected	Highest temperature = Oil temperature at initialization time \pm 5° C.	Oil temperature at initialization < 0° C. 10 < A/D of Oil temp sensor < 1000 Range = D, I, L, R DS_Active = TRUE RANGE = Q_NORMAL Not in Emergency mode	900 sec Continuous FATKO Type A
Temperature Sensor Circuit: High Input DS_Active = TRUE Drive time > 900 sec Engine coolant temperature > 50° C. Continuou Input Speed Sensor Circuit: No Signal P0717 Detects no Input Speed sensor pulses while detecting pulses from Output Speed sensor FAIL CASE 1 Range = D, I, or L FAIL CASE 1 FAIL CASE 1 No Signal Detects no Input Speed sensor pulses sensor FAIL CASE 2 Detects no pulse from Input Speed sensor while detecting 6 pulses from Output Speed sensor FAIL CASE 2 Count = 500 FAIL CASE 2 NA FAIL CASE 2 Digital signal < 45 or > 545 counts from Input Speed Sensor FAIL CASE 2 THEN Range from P, R, N to Drive: > 2.5 sec. FATKO Type A Count = 300 FAIL CASE 2 THEN Not in Emergency mode FAIL CASE 2 FATKO Type A Not in Emergency mode FAIL CASE 2 THEN Not in Emergency mode FAIL CASE 2 THEN Range from P, R, N to Drive: > 2.5 sec. FATKO Type A Range from P, R, N to Drive: > 8.0 sec. END IF Not shifting DS_Active = TRUE Not in Emergency mode FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 FAIL CASE 2	Temperature Sensor Circuit:	P0712	Detects A/D < 10	Count = 30 @ 10.0 sec	Not in Emergency mode	Continuous FATKO
Sensor Circuit: No Signal while detecting pulses from Output Speed sensor Detect no pulse from Input Speed sensor while detecting 6 pulses from Output Speed sensor Range = D, I, or L Output speed * expected gear ratio > 600 RPM IF N/A FAIL CASE 2 Digital signal < 45 or > 545 counts from Input Speed Sensor FAIL CASE 2 Digital signal < 45 or > 545 counts from Input Speed Sensor Trans Oil Temp > 20° C. THEN Range from P, R, N to Drive: > 2.5 sec. FATKO Type A Count = 300 Count = 300 FAIL CASE 2 Digital signal < 45 or > 545 counts from Input Speed Sensor Sensor Count = 300 FAIL CASE 2 For the Difference Count = 300 FAIL CASE 2 FAIL CASE 2 For the Difference FAIL CASE 2 FAIL CASE 2 FAIL CASE 2 For the Difference FAIL CASE 2 FAIL CASE 2 FAIL CASE 2	Temperature Sensor Circuit:	P0713	Detects A/D > 1000	Count = 12 @ 1.0 sec	DS_Active = TRUE Drive time > 900 sec Engine coolant temperature > 50° C.	-
$EM2 = 3^{rd} \text{ gear in } D$ $EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking}$ $EM4 = 5^{th} \text{ gear only in } D$ Pag	Input Speed Sensor Circuit: No Signal		while detecting pulses from Output Speed sensor	Detect no pulse from Input Speed sensor while detecting 6 pulses from Output Speed sensor Count = 500 FAIL CASE 2 Digital signal < 45 or > 545 counts from Input Speed Sensor Count = 300	FAIL CASE 1Range = D, I, or LOutput speed * expected gear ratio > 600 RPMIFVehicle speed > 66 km/hrORTrans Oil Temp > 20° C.THENRange from P, R, N to Drive: > 2.5 sec.ELSERange from P, R, N to Drive: > 2.5 sec.END IFNot shiftingDS_Active = TRUENot in Emergency modeGear $\ge 2^{nd}$ Not in B1 release controlNo faults: P0705, P0711, P0712, P0713, P0722FAIL CASE 2DS_Active = TRUENot in Emergency mode	FAIL CASE 2 100 msec continuously FATKO

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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No
					MIĽ)

Sensor: Low /oltage	P0722	Detects no vehicle speed when Input Speed signal is present	FAIL CASE 1 Detect no pulse from output speed sensor while detecting 12 pulses from input speed sensor Count = 500 FAIL CASE 2 Digital signal < 45 or > 545 counts from Output Speed Sensor Count = 300 @ 100 msec	FAIL CASE 1 Range = D, I, or L IF Vehicle speed > 66 km/hr OR Trans Oil Temp > 20° C. THEN Range from P, R, N to Drive: > 2.5 sec. ELSE Range from P, R, N to Drive: > 8.0 sec. END IF Not in Neutral control, not shifting DS_Active = TRUE Not in Emergency mode No faults: P0705, P0711, P0712, P0713, P0722 FAIL CASE 2 DS_Active = TRUE	FAIL CASE 1 15 sec. at 2000 RPM input speed 5 sec. at 6000 RPM input speed FAIL CASE 2 100 msec continuously FATKO Type A
Engine Speed Circuit Aalfunction	P0727	Engine speed information failure on CAN bus	TCM receives Engine Speed Validity = FALSE Count = 1	Not in Emergency mode 3.0 sec. after Ignition On OR Reset of counter DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults: U2105	4.0 sec. continuously FATKO Type A
Gear 1 Manual .ow fault S5 Off, SLU Off)	P0730	Compares Expected Ratio to Actual Ratio	Current Gear = 1 st engine braking Absolute value(1-Current Ratio/Expected Ratio) > 20% Count = 12 @ 1.0 sec.	$\begin{array}{l} 500 \leq \text{Output RPM} \leq 1260\\ \text{Throttle} = 0.0\%\\ 8.0 \text{ sec. after changing to D, I, L}\\ 0.5 \text{ sec. after shifting control}\\ \text{Oil temperature} \geq 20.0^{\circ} \text{ C.}\\ \text{Shift position} = L\\ \text{Engine speed} > 400 \text{ RPM}\\ \text{Ignition voltage} \geq 10.5 \text{ V}\\ \text{Not shifting, not in ND control}\\ \text{DS_Active} = \text{TRUE}\\ \text{No faults: P0705, P0711, P0712, P0713, P0717, P0722, P0727, P0741, P0962, P0963, P0966, P0967, P0970, P0971, P0973, P0974, P0976, P0977, P0979, P0980, P0982, P0983, P0985, P0986, P1781, P1791\\ \end{array}$	1.0 sec. continuously FATKO Type A

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	ACCEPTABLE OPERATING RANGE and CODE RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No MIL)
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Gear 1 ratio fault	P0731	Compares (Input speed/Output speed) to Commanded ratio	Current Gear = 1 st	500 \leq Output RPM \leq 1260 Throttle \geq 40.0%	1.0 sec. continuously
			Gear ratio =2.22 \pm 4%	Engine acceleration > 0 for 1.0 sec.	
				8.0 sec. after changing to D, I, L	FATKO
			Count =5 @ 1.0 sec	0.5 sec. after shifting control	Туре А
				Oil temperature $\geq 20.0^{\circ}$ C.	
				Shift position = D, I, L	
				Engine speed ≥ 400 RPM	
				Ignition voltage \geq 10.5 V	
				Not shifting, not garage shifting	
				Brake off, spinning = FALSE	
				DS_Active = TRUE	
				No faults: See P0730 + U2104, U2105	
Gear 2 ratio fault	P0732	Compares (Input speed/Output speed) to	Current gear = 2nd	Output RPM ≥ 500	1.0 sec.
		Commanded ratio		Throttle \geq 10%	continuously
			Absolute value(1-Current Gear/Expected Gear)	0.5 sec. after B1 clutch apply control finished	
			> 20%	8.0 sec. after changing to D, I, L	FATKO
				0.5 sec. after shifting control	Туре А
			Count = 12 @ 1.0 sec	Oil temperature $\geq 20.0^{\circ}$ C.	
				Shift position = D, I, L	
				Engine speed \geq 400 RPM	
				Ignition voltage \geq 10.5 V	
				Not shifting, not garage shifting	
				Brake off, spinning = False	
				DS_Active = TRUE	
				No faults: See P0730 + U2104, U2105	
Gear 3 ratio fault	P0733	Compares (Input speed/Output speed) to	Current gear = 3rd	Output RPM \geq 500	1.0 sec.
		Commanded ratio		Throttle ≥ 10%	continuously
			Absolute value(1-Current Gear/Expected Gear)	8.0 sec. after changing to D, I, L	FATKO
			> 20%	0.5 sec. after shifting control	FATKO
			for 1.0 sec. continuously	Oil temperature $\geq 20.0^{\circ}$ C.	Туре А
			Count = 12 @ 1.0 sec	Shift position = D, I, L	
			Count - 12 (g 1.0 Sec	Engine speed \geq 400 RPM	
				Ignition voltage \geq 10.5 V	
				Not shifting, not garage shifting	
				Brake off, spinning = False	
				DS_Active = TRUE	
				No faults: See P0730 + U2104, U2105	

Emergency Mode $1 = 5^{\text{th}}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 4 $EM8 = 5^{th}$ gear in D: 4th in L range

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	AULT ACCEPTABLE OPERATING RANGE and ODE RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No MIL)
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Gear 4 ratio fault	P0734	Compares (Input speed/Output speed) to Commanded ratio	Current gear = 4th	Output RPM ≥ 500 Throttle > 10%	1.0 sec. continuously
			Absolute value(1-Current Gear/Expected Gear) > 20%	8.0 sec. after changing to D, I, L 0.5 sec. after shifting control	FATKO
			x4thFail_SLT = ON	Oil temperature $\ge 20.0^{\circ}$ C. Shift position = D, I, L	Туре А
			Current Gear \neq 3 rd gear ratio ± 4%	Engine speed ≥ 400 RPM Ignition voltage ≥ 10.5 V	
			Count = 12 @ 1.0 sec	Not shifting, not garage shifting Brake off, spinning = False DS_Active = TRUE No faults: See P0730 + U2104, U2105	
Gear 5 ratio fault	P0735	Compares (Input speed/Output speed) to Commanded ratio	Current gear = 5th	No faults: See P0730 + 02104, 02105Output RPM \geq 500Throttle \geq 10%	1.0 sec. continuously
			Absolute value(1-Current Gear/Expected Gear) > 20%	8.0 sec. after changing to D, I, L 0.5 sec. after shifting control	FATKO
			Count = 12 @ 1.0 sec	Oil temperature $\geq 20.0^{\circ}$ C. Shift position = D, I, L	Type A
				Engine speed ≥ 400 RPM Ignition voltage ≥ 10.5 V Not shifting, not garage shifting	
				Brake off, spinning = False DS Active = TRUE	
				No faults: See P0730 + U2104, U2105	
Reverse Gear ratio fault	P0736	Compares (Input speed/Output speed) to Commanded ratio	Current gear = Reverse Absolute value(1-Current Gear/Expected Gear)	Output RPM \geq 500 8.0 sec. after changing to R	0.5 sec. continuously
			> 20%	0.5 sec. after shifting control Oil temperature $\ge 20.0^{\circ}$ C. Shift position = R	FATKO Type A
			Count = 12 @ 0.5 sec	Engine speed \geq 400 RPM Ignition voltage \geq 10.5 V	
				Not in NR control Brake off	
				DS_Active = TRUE Not in Emergency mode	
				No faults: See P0730 + P0562, P0563, P0601, U2104, U2105	

Emergency Mode 1 = 5th gear in D: 2nd in L range EM5 = 4th gear in D, no E/B EM9 = 5th gear in D: 2nd in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 5 $EM8 = 5^{th}$ gear in D: 4th in L range

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	DPERATING RANGE and PRIMARY MALFUNCTION DETENTIONALITY PARAMETERS	CTION SECONDARY MALFUNCTION PARAMETERS and CONDITIONS MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No MIL)
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Torque Converter Clutch System Performance: Slipping	P0741	Detects high Torque Converter slip when TCC commanded on (Lock-Up Slipping)	Engine RPM – Input speed > 100 RPM Count = 6 @ 2.0 sec	$\label{eq:constraint} \begin{array}{ c c c } Throttle \geq 20\% \\ 0.5 \mbox{ sec. after shifting control} \\ Engine \mbox{ speed } \leq 4000 \mbox{ RPM} \\ Shift \mbox{ position } = D, \mbox{ I}, \mbox{ L} \\ Not \mbox{ shifting} \\ Ignition \mbox{ voltage } \geq 10.5 \mbox{ V} \\ SLU \mbox{ (TCC PCS) target current } \geq 1000 \mbox{ mA} \\ Lock-up \mbox{ ON} \\ DS_Active = TRUE \\ Not \mbox{ in Emergency mode} \\ No \mbox{ faults: See P0730 + U2104, U2105} \end{array}$	≥ 2.0 sec. continuously FATKO Type A
Shift Solenoid C Stuck On	P0762	Hydraulic failure	Current gear = 5^{tn} Current gear ratio = 1.451 ± 4% Absolute value(1-Current Gear/Expected Gear) > 20% Current gear = 4^{th} for 1.0 sec continuously Increase SLT pressure IF Current Ratio = 3^{rd} ratio ± 4% Count = 12 @1.0 sec	Output RPM ≥ 500Throttle ≥ 10%8.0 sec. after changing to D, I, or L0.5 sec. after shifting controlOil temperature ≥ 20.0° C.Shift position = D, I, or LEngine speed ≥ 400 RPMIgnition voltage ≥ 10.5 VNot shifting, not garage shiftingBrake off, spinning = FALSEDS_Active = TRUENot in Emergency modeNo faults: P0562, P0563, P0601, P0705, P0711,P0712, P0713, P0717, P0722, P0727, P0741,P0744, P0962, P0963, P0966, P0967, P0970,P0971, P0973, P0974, P0976, P0977, P0979,P0980, P0982, P0983, P0985, P0986, P1719,P1781, P1791, U2104, U2105 checksum	1.0 sec. continuously FATKO Type A
Line Pressure PCS (SLT) Short to Ground, Open	P0962	Detects very low current through solenoid	Detects Input A/D < 68 (92 mA) Count = 25 @ 0.5 sec	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A
Line Pressure PCS (SLT) B+ Short	P0963	Detects very high current through solenoid	Detects Input A/D > 1000 (1356 mA) Count = 4 @ 0.5 sec	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A

Emergency Mode $1 = 5^{th}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range

EM2 = 3^{rd} gear in D EM3 = 4^{th} gear in D, no Engine Braking EM6 = 3rd gear in D, no E/B EM7 = 5^{th} gear in D: 2^{nd} in L range GMT315MATRIX03.DOC 3/25/03 $EM4 = 5^{th}$ gear only in D page 6 $EM8 = 5^{th}$ gear in D: 4th in L range

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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No
					MIL)

Torque Converter Clutch (TCC) PCS (SLU) Short to Ground, Open	P0966	Detects very low current through solenoid	Detects Input A/D < 68 (92 mA) Count = 25 @ 0.5 sec	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A
Torque Converter Clutch (TCC) PCS (SLU) B+ Short	P0967	Detects very high current through solenoid	Detects Input A/D > 1000 (1356 mA) Count = 4 @ 0.5 sec	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A
Shift Pressure PCS (SLS) Short to Ground, Open	P0970	Detects very low current through solenoid	Detects Input A/D < 68 (92 mA) Count = 25 @ 0.5 sec	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A
Shift Pressure PCS (SLS) B+ Short	P0971	Detects very high current through solenoid	Detects Input A/D > 1000 (1356 mA) Count = 4 @ 0.5 sec.	Not in Emergency mode DS_Active = TRUE	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid A Short to Ground	P0973	Detects Short to Ground	Detects OFF signal of S1 monitor, when S1 driver outputs ON signal Count =1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S1 output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid A B+ Short, Open	P0974	Detects Short to Power or Open	Detects ON signal of S1 monitor, when S1 driver outputs OFF signal Count =1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S1 output changes	≥ 500 msec. Continuous FATKO Type A

Emergency Mode $1 = 5^{\text{th}}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 7 $EM8 = 5^{th}$ gear in D: 4th in L range

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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No
					MIL)

Shift Solenoid B Short to Ground	P0976	Detects Short to Ground	Detects OFF signal of S2 monitor, when S2 driver outputs ON signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S2 output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid B B+ Short, Open	P0977	Detects Short to Power or Open	Detects ON signal of S2 monitor, when S2 driver outputs OFF signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S2 output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid C Short to Ground	P0979	Detects Short to Ground	Detects OFF signal of S3 monitor, when S3 driver outputs ON signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S3 output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid C B+ Short, Open	P0980	Detects Short to Power or Open	Detects ON signal of S3 monitor, when S3 driver outputs OFF signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S3 output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid D Short to Ground	P0982	Detects short to ground	Detects OFF signal of S4 monitor, when S4 driver outputs ON signal Count = 1	not in Emergency mode DS_Active = TRUE 25 msec. after solenoid output changes	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid D B+ Short, Open	P0983	Detects Short to Power or Open	Detects ON signal of S4 monitor, when S4 driver outputs OFF signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S4 output changes	≥ 500 msec. Continuous FATKO Type A

Emergency Mode $1 = 5^{\text{th}}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 8 $EM8 = 5^{th}$ gear in D: 4th in L range

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SENSED PARAMETER	FAULT CODE	ACCEPTABLE OPERATING RANGE and RATIONALITY	PRIMARY MALFUNCTION DETECTION PARAMETERS	SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No
					MIL)

Shift Solenoid E Short to Ground	P0985	Detects Short to Ground	Detects OFF signal of S5 monitor, when S5 driver outputs ON signal	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S5 output changes Count = 1	≥ 500 msec. Continuous FATKO Type A
Shift Solenoid E B+ Short, Open	P0986	Detects Short to Power or Open	Detects ON signal of S5 monitor, when S5 driver outputs OFF signal Count = 1	Not in Emergency mode DS_Active = TRUE 25 msec. after solenoid S5 output changes	≥ 500 msec. Continuous FATKO Type A
Incorrect Shifting	P1719	Detects tie-up, engine flare, long shift time, or rapid shifting	Shift position = D, I, L Oil temperature $\geq 60^{\circ}$ C. No multiplex shifting Condition A (tie-up) OR Condition B (engine flare) OR Condition C (long shift time) OR Condition D (rapid shifting)	No multiplex shifting DS_Active = TRUE Not in Emergency mode No faults: P0711, P0712, P0713, P0722, P0727, P1781	Count = 5 FATKO Type A
Driver- Requested Torque CAN Signal Error	P1779	Driver-requested torque signal failure on CAN bus	TCM receives Driver-Requested Torque validity = FALSE Count = 1 @ 4.0 sec	3.0 sec. after Ignition On OR Controller reset DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults: U2105	4.0 sec. continuously FATKO Type A
CAN Torque Reduction Signal Error	P1780	CAN torque reduction information failure on CAN bus	TCM receives Engine Torque Reduction validity = FALSE Count = 5 @ 4.0 sec	3.0 sec. after Ignition On OR Controller reset DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults: U2105	4.0 sec. continuously FATKO Type A
Engine Torque Circuit Malfunction	P1781	Engine torque information failure on CAN bus	TCM receives Engine Torque validity = FALSE Count = 1	3.0 sec. after Ignition On OR Controller reset DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults: U2105	4.0 sec. continuously FATKO Type A

Emergency Mode $1 = 5^{\text{th}}$ gear in D: 2^{nd} in L range EM5 = 4^{th} gear in D, no E/B EM9 = 5^{th} gear in D: 2^{nd} in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 9 $EM8 = 5^{th}$ gear in D: 4th in L range

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SENSED PARAMETER	FAULT ACCEPTABLE OPERATING RANGE and CODE RATIONALITY		TION SECONDARY MALFUNCTION PARAMETERS and CONDITIONS	MONITORING TIME LENGTH and DTC TYPE A (MIL), B (MIL NIC), C (No MIL)
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Pedal Position Circuit Malfunction	P1791	Pedal Position information failure on CAN bus	TCM receives Pedal Position validity = FALSE Count =1	3.0 sec. after Ignition On OR Controller reset DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults U2105	4.0 sec. continuously FATKO Type A
Engine Coolant Temperature CAN Signal Error	P1792	Engine coolant temperature signal failure on CAN bus	TCM receives Engine Coolant Temperature validity = FALSE Count = 1	3.0 sec. after Ignition On OR Controller reset DS_ACTIVE_CAN = TRUE Not in Emergency mode No faults: U2105	4.0 sec. continuously FATKO Type A
CAN Bus Off Counter Overrun Error	U2104	CAN Bus Off Counter Overrun error	TCM receives "BUS OFF" state from CAN controller a number of times Count = 1	3.0 sec after Ignition On OR Controller reset DS_Active_CAN = TRUE	Count = 1 FATKO Type A
CAN Error: Lost Communication to ECM	U2105	Lost communication with ECM	TCM cannot detect frame of GENERAL STATUS ECM Count = 1	3.0 sec after Ignition On OR Controller reset DS_Active_CAN = TRUE Not in Emergency Mode	4.0 sec. continuously FATKO Type A
CAN Error: Lost Communication to BCM	U2107	Lost communication with BCM	TCM cannot detect frame of GENERAL STATUS BCM Count = 1	3.0 sec after Ignition On OR Controller reset DS_Active_CAN = TRUE Not in Emergency Mode	4.0 sec. continuously FATKO Type A
CAN Error: Lost Communication to ABS/TC Control Module	U2108	Lost communication with ABS	TCM cannot detect frame of GENERAL STATUS ABS Count = 1	3.0 sec after Ignition On OR Controller reset DS_Active_CAN = TRUE Not in Emergency Mode	4.0 sec. continuously FATKO Type A

Emergency Mode 1 = 5th gear in D: 2nd in L range EM5 = 4th gear in D, no E/B EM9 = 5th gear in D: 2nd in L range $EM2 = 3^{rd} \text{ gear in } D \qquad EM3 = 4^{th} \text{ gear in } D, \text{ no Engine Braking} \\ EM6 = 3rd \text{ gear in } D, \text{ no } E/B \quad EM7 = 5^{th} \text{ gear in } D: 2^{nd} \text{ in } L \text{ range} \\ GMT315MATRIX03.DOC \qquad 3/25/03$

 $EM4 = 5^{th}$ gear only in D page 10 $EM8 = 5^{th}$ gear in D: 4th in L range