NOTE: Printing this file may require 8.5" x 14" (legal size) paper, depending on your printer setup.

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Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
atalyst Bank 1	P0420	oxygen storage of catalyst	normalized oxygen storage	<	1	factor	<1factor	exhaust gas mass flow	>	8.33	g/sec	>8.33g/sec	approx.	0.01 sec	0.4 sec	two driving
			less than normalized oxygen storage					exhaust gas mass flow	<	27.78	g/sec	<27.78g/sec	1000 sec		continuous	cycles each
			of a limit catalyst					catalyst temp.	<	700	° C	<700° C	during	one	or 4 sec	with: 0.4 sec
								catalyst temp. model	>	390	°C	>390° C	active	completed	cumulative	continuous
								engine speed	>	1000	rpm	>1040rpm	driving	test per		or 4 sec
								engine speed	<	3520	rpm	<3520rpm		driving		cumulative
								engine load engine load	> <	14 17 4255	% %	>14 17% <4255%	one test	cycle		
								modeled catalyst temp. gradient	<	2.5	° C / sec	<2.5° C / sec	(average			
								exhaust gas mass flow gradient	<	8.33	g/sec²	<8.33g/sec ²	of 4			
								fuel system closed loop	active	-	-	active	checks)			
								time after engine start	>	235	sec	>235sec	per driving			
								ambient temperature	>	-48	° C	>-48° C	cycle			
								scheduled by System Manager secondary O2	TRUE	-	-	TRUE ready				
								sensor fuel adaptation	FALSE			FALSE				
								fault short term fuel trim	<	1.25	factor	<1.25factor				
								(< max) short term fuel trim	>	0.75	factor	>0.75factor				
								(> min) transient fuel control	FALSE			FALSE				
								critical misfire rate detected	FALSE			FALSE				
								cat. damaging misfire rate exceeded	FALSE			FALSE				
								cat oxygen storage neutralization	FALSE			FALSE				
Misfire		crankshaft speed	emissions relevant misfire rate	>	1.3	%	>1.3% (emission relevant misfire rate = 1.5%)		>	450	rpm	>450rpm	1000 revs	cylinder	immediate	Fault during
Emission Level		fluctuation cylinde 1 to	r				3,73)	engine speed	<	6500	rpm	<6500rpm		firing		1st interval:
Multiple Cylinder	P0300	cylinder 6						indicated torque (idle, no drive)	>	3.91	%	>3.91%		frequency		2 faults in
Cylinder #1	P0301							indicated torque (drive) (MISALUN)	>	3.91 17.19	%	>3.91 17.19%			After	2 different
Cylinder #2	P0302							engine speed	<	12800	rpm/sec	<12800rpm/sec (not active)		continuous	detection,	drive cycles.

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Cylinder #3	P0303							volumetric efficiency gradient	<	768	%/rev	<768%/rev (not active)			the	
Cylinder #4	P0304							cylinder events after engine start	>	6	ignitions	>6ignitions			diagnostic	Fault during
Cylinder #5	P0305							air temperature	>	-30	°C	>-30° C			can only	remaining
Cylinder #6	P0306							rough road	not detected	-	-	not detected			pass if	intervals:
								traction control	off	-	-	off			similar	8 faults in 2
								clutch switch press / release	off	-	-	transitionFALSE-			conditions	different
								leak detection	off	-	-	off			are	drive cycles
								active handling	not active			not active			encountered	with at least
								ABS	not active	-	-	not active				4 faults in
								engine drag control	not active	-	-	not active				each.
								fuel cut off	not active	-	-	not active				
								fuel level	>	5.9	%	> 5.93 %				
								OR fuel level	<	5.9	%	> 5.93 %				
								AND solid misfire MIL	on	-	-	on				
								OR fuel level	set	-	-	set				
								error: throttle	not set	-	-	not set				
								error: crankshaft sensor	not set	-	-	not set				
								error: ref.mark of	not set	-	-	not set				
								crank sensor								
										-	-					
										-	-					
										-	-					
0 . 1 . 10			OR		10.0	0/	40.0						1000			F
Catalyst Damaging Level			Catalyst damaging misfire rate	>	16.2 6.8	%	>16.2 6.8%	Includes all the above with the					1000 revs			First
Multiple Cylinder	P0300				see Misfire		see Misfire	following exceptions:					First interval			occurance:
Cylinder #1	P0301				supplemental		supplemental	First interval extention					200 revs			immediate
Cylinder #2	P0302				data		data	engine coolant temperature	<	-48	°C	<-48°C	all remaining			flashing
Cylinder #3	P0303				(h) (2.5.1)		(h) (2.5.1)	fuel level	>=	6.19	%	> 6.19 %	intervals			while error
Cylinder #4	P0304				(/(- /		1 // /	OR fuel level	<	6.19	%	> 6.19 %				present, then
Cylinder #5	P0305							AND blinking MIL	blinking	-	-	blinking				no MIL
Cylinder #6	P0306							AND NOT first	-	-	-					with no error.
								blink event				+				
																Second
																occurance:
																immediate
					+						1			1	1	flashing while error
					1						1					present, then
																solid MIL
																with no error.
evaporative system																
canister ventilation	P0446		tank pressure too	<	-10.50049	hPa	< -10.50049 hPa	а	>=	-9.8	°C	>= -9.8 °C	< 20 sec	once per dcy	2,6 secs	2 dcy
valve (AAV)		pressure while	low because					ambient temperature								-

Component/	Fault	Monitor Strategy Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		AAV is open and CPV is closed canister vent. defective & closed					ambient temperature	<=	45	°C	<= 45 °C				
							ambient pressure	>=	680.00	hPa	>= 680.00 hPa				
							vehicle speed	<=	1,86	mph	<= 1,86 mph				
							engine is in idle mode	true			true				
							unfiltered tank pressure	>=	-18.00	hPa	>= -18.00 hPa				
							and unfiltered tank pressure	<=	10.00	hPa	<= 10.00 hPa				
canister purge valve (CPV)	P0496	monitoring of tank pressure while final pressure too low because	<	-1.00098	hPa	< -1.00098 hPa	battery voltage	>=	10.45	V	>= 10.45 V	ca. 10 sec	once per dcy		
		CPV and AAV are closed CPV defective and open		-1.00098			and battery voltage	<=	18.00	V	<= 18.00 V				
		closed open					lambda control is	true			true				
							secondary air	true			true				
							pump inactive secondary air diagnosis inactive	true			true				
							air bag hasn't been	true			true				
							no torque reduction (e.g.	true			true				-
							resulting from switched-off cylinder)								
	P0497	monitoring of tank pressure while closed					critical misfire rate	false			false				
		CPV and AAV are closed					ratio intake manifold pressure /ambient pressure	<	0.602		< 0.602				
							fault of canister purge valve in actual driving cycle	false			false				
tank leak large	P0455	AAV is closed and vacuum pressure CPV is open built up gradient too low	<	0.450039 0.750065	hPa/s	=CONCATENATE E93," ",F93," ",G93)	fault of canister ventilation valve in actual driving cycle	false			false	ca. 18 sec	once per dcy		
		because of large tank leakage					tank fuel level	>=	3.900	I	>= 3.900 l				
		(for example: open gas filler cap)					and tank fuel level	<=	55.100	I	<= 55.100 l				
							enabled by diagnostic	true			true				-
							scheduler fuel system adaptation has completed	true			true				
							or time since engine start exceeds	>	600	sec	> 600 sec				
							threshold								

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Fuel Evaporative System	P0456	Monitor fuel tank's pressure after engine shutdown						Engine off natural vacuum diagnosis has not been performed in this driving cyle.	true				100ms in	once per dcy	2.6 secs	2dcy
								Fuel evaporative system monitor (at engine on) didn't run nor detect large leak nor a tight system.	true				afterrun			
								Engine coolant temperature at start.	<=	42.0	°C	true				
								engine coolant temp. At start - intake air temp.	<=	6.8	°C	true				
								intake air temperature	<=	35.3	°C	true				
								intake air temperature	>=	3.8	°C	true				
								ambient air temperature	<	36.8	°C	true				
								ambient air temperature	>	2.3	°C	true				
								engine has been running for a cal. min. time	>	600.00	S	true				
								engine coolant temp. at engine stop	>	59.3	°C	true				
								driving distance (in current dcy) covered	>=	8100.0	m	true				
								charcoal canister load factor	<	10.00	-	true				
								ambient pressure	>=	680.0	hPa	true				
								driving distance (for vehicle lifetime) covered	>	20	Km	true				
								the fuel tank's level isn't at its minimum	true							
								the fuel tank's level isn't at ist maximum	true							
								battery's voltage no refueling activity	> true	11.00	V	true				
								the fuel tank pressure is within cal. range	true							
								no intake air temperature faults	true							
								no the purge control system faults	true							

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								no faults of the	true							
								purge control								
								valve's power								
								stage no vehicle speed	true							
								sensor faults								
								no engine coolant	true							
								temperature sensor faults								
								no tonk progouro	true							
								no tank pressure sensor rationality	uue							
								faults								
								no tank pressure	true							
								sensor range faults								
								no power supply voltage faults	true							
								no main load	true							
								sensor faults								
								no canister vent	true							
								valve faults								
								no canister	true							
								ventilation valve's								
								power stage faults								
								no ambient	true							
								pressure sensor								
								faults								
		Close canister														
		ventilation														
		valve. Look for maximum														
		pressure.														
		procoure.														
		Abort if:														
		- max. pressure >=														
		threshold.	max. pressure	>=	volume & ambient temperature dependent	hPa										
							1									
		- max. pressure -														
		current pressure >=	max. pressure -	>=		hPa	>= 0.30029 hPa									
		threshold.	current pressure	/-	0.30029	пга	>= 0.30029 IIFa	' [
		- pressure stays in		>=		hPa	>= -0.69946 hPa	i l								-
		range			-0.69946											
		near zero for	pressure	<=	0.69946	hPa	<= 0.69946 hPa									
		a specific time.			500	S	500 s									
		- pressure <= threshold	proceuro		-0.74951	hPa	<= -0.74951 hPa									
		for a specific time	pressure	<=	30.00	nPa s	<= -0.74951 hPa 30.00 s	1								
		ioi a specific time			50.00	3	30.00 8									
		(vacuum build-up instead														
		of pressure build-					+							1		
		up)														
		- pressure-phase-					1									
		time														
		>= threshold.	pressure phase time	>=	2400.00	S	>= 2400.00 s		-							
							1									

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		- diagnostic-time														
		>= threshold	diagnostic time	>=	2900.00	s	>= 2900.00 s									
		correct max. pressure.														
		procedio.														
		open canister ventilation														
		valve for a			400.00	S	400.00 s									
		calibrated time.														
		Look for minimum														
		pressure														
		Abort if:														
		- min pressure <=														
		threshold	min. pressure	<=			<=									
		- diagnostic time														
		>= threshold	diagnostic time	>=	2900.00	s	>= 2900.00 s									
		current pressure - min.														
		- pressure >=	current pressure -	>=		hPa	>= 0.30029 hPa									-
		threshold AND	min. pressure		0.30029											
		min. pressure <=														
		threshold	min. pressure	<=	-0.69946	hPa	<= -0.69946 hPa									
		- pressure stays in	pressure	>=		hPa	>= -0.69946 hPa									
					-0.69946	LD-	0.00040 h D-									
		ambient range for a	pressure	<=	0.69946	hPa	<= 0.69946 hPa									
		specific time			500.00	S	500.00 s									
		- canister vent														
		valve re-														
		opened for a more than N times	no. canister vent valve openings	>	2		> 2									
		ulail N ullies	vaive openings													
		because the														
		pressure exceeds a	pressure			hPa	0.74951 hPa									
		threshold	•		0.74951											
		Calculate														
		difference														
		between corrected														
		max. pressure and min.					1									
		pressure.					1									
		Calculate														-
		normalized result. First divide														
		the														
		pressure														
		difference by a							[1	I			

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		parameter. Then subtract			volume & ambient temperature dependent											
		this result from 1.														
		Filter the normalized														
		result with an														
		EWMA														
		filter.														
		Compare filtered	Filtered result	>			> 0.399994									
		result			0.399994											
		with threshold. N results will be			4		4									
		taken			4		4									
		into account in														
		order to														
		determine a pass.														
		A fault will be indicated														
		immediately.														
	5.444												_			
secondary air system	P0411	check	relative secondary air mass flow. Ratio from	<	0.273		< 0.273	start with catalyst heating	active				< 5s	one	2.6 sec	2 dcy
			calculated secondary air mass					secondary air system	active							
			by oxygen sensor signal and													
			secondary air mass model													
								HO2S sensor	active					complete		
								specific values intake air	>	0	°C	> 0 °C		test per dcy		
								temperature								
								intake air temperature	<	80.3	°C	< 80.3 °C		(only, if		
								engine coolant	>	5.3	°C	> 5.3 °C		secondary-		
								temperature engine coolant	<	120	°C	< 120 °C		air-system		
								temperature	_	120	C	< 120 C		all-system		
								ratio: (MAP Model / Baro)	<	0.7		< 0.7		was active)		
								no error on altitude detection	avtive							
								fuel trim error misfire	false false							
							1	error: multiple	false							
								misfire								
								error: HFM error: intake air	false false							
								error: make air	false							
								temperature								
								error: secondary air pump (power	false							
							1	IAIT DUTTIN (DOWER		1	1	1	I .		1	

System	Code Description	Signal and Criteria	Logic	Value	Units	0 1:4:			17.1					, .	
			Ì			Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
							error: canister purge system diagnosis	false							
							error: canister purge valve power	false							
							stage error: power supply	false							
							voltage UB	iaise							
							error: lambda sensor heating	false							
							upstream cat error: fault from	false							
							diagnostics of fuel supply system								
							error: lambda sensor upstream catalyst	false							
							catalyst condition for basic mixture adaptation	false							
							disabled								
							enabled by the diagnostic	true							
							scheduler								
							fuel cut off mixture adaptation	false active							
							for secondary air diagnosis is in								
							steady state								
							mass airflow mass airflow	> <	6 150	kg/h	> 6 kg/h < 150 kg/h				
							change in air charge per working cycle	<=	7	kg/h %	<= 7 %				
							2,5								
_	active flow check	relative secondary	<	0.555 - 0.531		< 0.555 - 0.531	all other enabling					< 10s			
	active now circon	air mass flow. Ratio from		0.333 - 0.331		V 0.335 - 0.351	conditions					V 103			
	seperate/addition enable conditions	calculated secondary air mass by oxygen					as for passive functional check								
	different threshol	d sensor signal and secondary air mass model													
		model					mass airflow	<	6	kg/h	< 6 kg/h				
							mass airflow	>	100	kg/h	> 100 kg/h				
							change in air charge per working cycle	>=	-7	%	>= -7 %				
							change in air charge per working cycle	<=	7	%	<= 7 %				
							engine idle	true							
							vehicle speed	<	2.5	km/h	< 2.5 km/h				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								integrated air mass flow from engine start to max. value	>	0.499	kg	> 0.499 kg				
								time counter at end of start	>	143.5	sec	> 143.5 sec				
								condition filter frm deviation inside the allowed area	>	-0.119		> -0.119				
									<	0.119		< 0.119				
								release of active diagnosis from permitted numbers of active	active							
								diagnosis								
uel System Rich/Lean	P2191		delta lambda correction	>	1.175	factor	>1.175factor	fuel system status	closed loop	-	-	closed loop	approx.	0.1 sec	0.4 sec	two driving
Multiplicative	P2192	range - multiplicative	or delta lambda correction	<	0.825	factor	<0.825factor	long term fuel trim status	active	-	-	active	300 sec	continuous	continuous	cycles each
nd Additive		(load > threshold and air flow > threshold)						engine coolant temperature	>	50.3	°C	>50.3°C	from engine		or 4 sec	with: 0.4 sec
	P2187		delta fuel load correction	>	5.25	%	>5.25%	purge control	not active	-	-	not active	start (after		cumulative	continuous
	P2188	low speed and low load	or delta fuel load correction	<	-5.25	%	<-5.25%	intake air temperature	<=	65.3	°C	<=65.3°C	adaptation			or 4 sec
								fuel level	>	6.19	%	> 5.92 %	has		After	cumulative
								or fuel level error integrated air mass	set >=	2800	g g	set >=2800g	stabilized)		detection, diagnostic	
															can only pass if	
															similar	
															conditions are	
															encountered	
emand controlled uel supply																
(DECOS)	P0088	difference between measured	fuel rail pressure difference	<	- 150	kPa	< - 150 kPa	DECOS fuel pump is active	true			true	5 sec	continuous	0.2 sec	2 dcy
		and set-point fuel rail pressure						DECOS fuel control is enabled	true			true				
								time after engine start	>	1	sec	> 1 sec				
	P0089	difference between actual necessary and	duty cycle difference	<	-25	%	< -25 %	time after hot start	>	6	sec	> 6 sec				
		pre-control duty cycle						- fuel pressure								
		, ,						sensor								
								(DECOS) - power stage of demand	true			true				
I					l .	l .	1	iueillallu			1	1	l .	1	1	1

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0087	difference between measured	fuel rail pressure	>	150	kPa	> 150 kPa	DECOS fuel pump is active	true			true				
		and set-point fuel rail pressure	difference					DECOS fuel control is enabled	true			true				
								time after engine	>	1	sec	> 1 sec				
	P0089	difference between actual	duty cycle difference	>	25	%	> 25 %	time after hot start	>	6	sec	> 6 sec				
		necessary and pre-control						no fault of								
		duty cycle						- low pressure fuel sensor (DECOS)	true			true				
								- power stage of demand	uuc			ilde				
								controlled fuel pump	true			true				
								no empty or almost empty fuel tank	true			true				
								CONTR								
uel pressure sensor (DECOS)	P0193	cirtcuit continuity -	managered concer		4.7	V	> 4.7 V	fuel cumply evetem	truo			truo	0.5 sec	antinuous	0.2 sec	2 day
	P0193	high or open	voltage measured sensor	>	0.3	V	< 0.3 V	fuel supply system is active	true			true	0.5 Sec	continuous	0.2 sec	2 dcy
		low	voltage													
	P0193	range check - high	measured fuel pressure	>	680	kPa	> 680 kPa						5 sec			
	P0192	range check - low		<	60	kPa	< 60 kPa	fuel supply system	true			true	5 sec			
			pressure					is active time after power fail	>=	360	sec	>= 360 sec				
Diagnosis of Power Control Module								general enabling conditions					0.6 sec	continuous	0.2 sec	2 dcy
								battery voltage	>	18 10	V	< 18 V > 10 V				
								locking request immobilizer	false			false				
	P0092	diagnosis short circuit to battery voltage						special enabling condition								
		only active if powerstage on	backward powerstage voltage of	>	3.9014	V	> 3.9014 V	condition output duty cycle PCM	true			true				
			fuel pump diagnosis					for power on diagnosis								
			and backward powerstage voltage of	>	2.7979	V	> 2.7979 V									

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
			fuel pump													
			diagnosis and													
			duty cycle PCM	<	100	%	< 100 %									
		diagnosis short						condition output	false			false				
		circuit to battery voltage						duty cycle PCM								
		voltage	backward	>	3.9014	V	> 3.9014 V	for power off								
		only active if	powerstage voltage					diagnosis								
		powerstage off	of fuel pump													
			diagnosis													
	P0091	diagnosis short						condition output	true			true				
		circiut to ground	b a alous and		0.0400		0.0400.1/	duty cycle PCM								
		only active if	backward powerstage voltage	<=	2.3486	V	<= 2.3486 V	for power on diagnosis								
		powerstage on	of					ulagi loolo								
			fuel pump													
			diagnosis and													
			duty cycle PCM	>	0	%	> 0 %									
	P0090	diagnosis wire						condition output	true			true				
		interruption	bookward		2.4414	V	> 2.4414 V	duty cycle PCM for power on								
		only active if	backward powerstage voltage	>	2.4414	V	> 2.4414 V	diagnosis								
		powerstage on	of					g								
			fuel pump													
			diagnosis and													
			duty cycle PCM	<	100	%	< 100 %									
			and													
			max-fault;	false			false									
			powerstage diagnosis													
		diagnosis wire	backward	>	2.4414	V	> 2.4414 V	condition output	false			false				
		interruption	powerstage voltage					duty cycle PCM								
		only active if	fuel pump					for power off								
		powerstage off	diagnosis					diagnosis								
			and													
			backward powerstage voltage	<	3.9014	V	< 3.9014 V									
			of													
			fuel pump													
	P0090	noworstone lest-	diagnosis	tru -			4									
	P0090	powerstage locked	message of PCM	true			true									
			powerstage is													
			locked													
r / Fuel Ratio																
ensor (primary																
F) ensor voltage		A/F sensor voltage	e A/F sensor voltage	>	3.7	V	>3.7V	A/F sensor heater	TRUE	-	-	TRUE	10 sec	0.1 sec	0.4 sec	two drivin
ank 1 sensor 1	P0130	exceeds threshold	_					at operating						continuous	continuous	cycles ead
	. 3.00							temperature								-
			A/F sensor voltage	<	4.81	V	<4.81V	engine starting	complete	-	-	complete	additional		or 4 sec	with: 0.4 s
		range						desired A/F	<	1.6	lambda	<1.6lambda	time if		cumulative	continuo
								all injectors	TRUE	-	-	TRUE	fuel level		Cumulative	or 4 sec
			or]			activated								

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								scheduled by System Manager	TRUE	-	-	TRUE	is low and			cumulative
			AF sensor voltage	>	2.5	V	>2.5V						not failed			
			and A/F sensor voltage		3.06	V	<3.06V						600 sec			
			A/F sensor voltage	<	3.00	v	<3.06V									
			(if using rich													
			calibration curve characteristic													
ir / Fuel Ratio																
ensor (primary /F)																
itegrated circuit																
ank 1	P0130	A/F sensor voltage	A/F sensor voltage IC corrective value	>	0.1	V	>0.1V	battery voltage	<	18	V	<18V	10 sec	0.1 sec	0.4 sec	two driving
		IC correction too						battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles ead
		, and the second						engine	running	-	-	running			or 4 sec	with: 0.4 s
								engine starting	complete	-	-	complete			cumulative	or 4 sec
																cumulativ
		A/F sensor IC operating voltage	low voltage	=	TRUE	-	=TRUE-	battery voltage	>	10.7	V	>10.7V	10 sec			
		too low						battery voltage	<	18	V	<18V				
						-	-	engine	running	-	-	running				
						-	-	engine starting	complete	-	-	complete				
		A/F sensor IC SPI interface	communication error	=	TRUE		=TRUE		>	10.7	V	>10.7V				
		communication error							<	18	V	<18V				
		A/F sensor IC circuit write error	write error	=	TRUE		=TRUE		running	-	-	running				
		at INIT register							complete	-	-	complete				
ir / Fuel Ratio																
ensor (primary /F)																
umping current ircuit open		lambda control factor change	absolute value of lambda control factor	>	0.025	lambda	>0.025lambda	battery voltage	<	18	V	<18V	1.5 sec	0.1 sec	0.4 sec	two drivin
ank 1 sensor 1	P2239	above threshold	change from the point when the					battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles eac
			secondary conditions are met					engine	running	-	-	running			or 4 sec	with: 0.4 se
								engine starting	complete	-	-	complete			cumulative	continuou
								A/F sensor voltage	<	1.51	V	<1.51V			Cumulative	or 4 sec
								A/F sensor voltage		1.49	V	>1.49V		1	1	cumulative

Component/	Fault	Monitor Strategy Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
							A/F sensor electrical trimming	not active	-	-	not active				
							A/F sensor heater at op.temp.	TRUE	-	-	TRUE				
							A/F sensor warm up control	complete	-	-	complete				
							lambda closed loop control	TRUE	-	-	TRUE				
							forced fuel trim amplitude	TRUE	-	-	TRUE				
							fuel trim forced amplitude	>	0.015	lambda	>0.015lambda				
							catalyst warm up	stable	-	-	stable				
							sec. O2 sensor proportional trim	stable	-	-	stable				
							lean mixture inhibit	FALSE	-	-	stable FALSE				
							loop control init		-	-	FALSE				
Air / Fuel Ratio							startup								
Sensor (primary VF)															
oumping current circuit open		A/F sensor voltage within upper	<	1.51	V	<1.51V	battery voltage	<	18	V	<18V	approx.	0.1 sec	0.4 sec	two driving
oank 1 sensor 1	P2237	and lower and A/F sensor thresholds voltage	>	1.49	V	>1.49V	battery voltage	>	10.7	V	>10.7V	8 sec	continuous	continuous	cycles each
		and desired lambda is outside					engine	running	-	-	running	once the		or 4 sec	with: 0.4 sec
		of upper or lower threshold					engine starting	complete	-	-	complete	driving		cumulative	continuous
							target lambda above upper limit	>	1.01	lambda	>1.01lambda	condition			or 4 sec
							or below lower limit	<	0.99	lambda	<0.99lambda	is met			cumulative
							closed loop control	TRUE	-	-	TRUE				
							A/F sensor heater	TRUE	-	-	TRUE				
							at operating temperature								
							A/F sensor electrical trimming	not active	-	-	not active				
							A/F sensor dynamic response	not slow	-	-	not slow				
							error: A/F sensor heating	not set	-	-	not set				
							integrated exhaust gas mass	>	400	g	>400g				
ir / Fuel Ratio ensor (primary /F)															

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
oumping current circuit open		A/F sensor not lean enough	A/F sensor voltage	<	1.7	V	<1.7V	battery voltage	<	18	V	<18V	5 sec	0.1 sec	0.4 sec	two driving
pank 1 sensor 1	P2238	during fuel shut off operation						battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles each
								engine	running	-	-	running			or 4 sec	with: 0.4 sec
								engine starting	complete	-	-	complete			cumulative	continuous
								time after fuel shut off	>	3	sec	>3sec				or 4 sec
								A/F sensor heater	TRUE	-	-	TRUE				cumulative
								at operating temperature								
Air / Fuel Ratio Sensor (primary A/F)																
reference voltage circuit open		A/F sensor voltage	A/F sensor voltage	<	0.2	V	<0.2V	battery voltage	<	18	V	<18V	2 sec	0.1 sec	0.4 sec	two driving
bank 1 sensor 1	P2243	above upper threshold	A/F sensor voltage	>	4.7	V	>4.7V	battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles each
		or below lower threshold						engine	running	-	-	running			or 4 sec	with: 0.4 sec
								engine starting	complete	-	-	complete			cumulative	continuous
			for time	>	1	sec	>1sec	A/F sensor heating normal	>	10	sec	>10sec				or 4 sec
								operation range for time								cumulative
								error: A/F sensor heater circuit	not set	-	-	not set				
								A/F sensor internal resistance	>	1500	Ohms	>1500Ohms				
Air / Fuel Ratio Sensor (primary A/F)																
reference ground circuit open		measured A/F sensor internal	A/F sensor internal resistance	>	1500	Ohms	>1500Ohms	battery voltage	<	18	V	<18V	5 sec	0.1 sec	0.4 sec	two driving
bank 1 sensor 1	P2251	resistance above upper threshold						battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles each
								engine	running	-	_	running			or 4 sec	with: 0.4 sec
			for time	>	5	sec	>5sec	engine starting	complete	-	-	complete			cumulative	continuous
								A/F sensor voltage	<	1.48	V	<1.48V				
								A/F sensor voltage	>	1.36	V	>1.36V				
								error: A/F sensor heater circuit	not set			not set				
								A/F sensor pump voltage shut off	FALSE	-	-	FALSE				
								A/F sensor warm up control	complete	-	-	complete				
								A/F sensor heater operation time	>	28	sec	>28sec				
+								engine run time	>	28	sec	>28sec		1		
								battery voltage below heater		-						
								switch off voltage for time	>	28	sec	>28sec				
								fuel cut in time	>	28	sec	>28sec				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								for a fuel cut off time	>	10	sec	>10sec				
								battery voltage exceed 11V time	>	28	sec	>28sec				
Air / Fuel Ratio																
Sensor (primary VF)																
neasuring (trim)		A/F sensor voltage	A/F sensor voltage	>	4.81	V	>4.81V	battery voltage	<	18	V	<18V	2 sec	0.1 sec	0.4 sec	two driving
circuit open		above threshold						battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles each
ank 1 sensor 1	P2626							engine	running	-	-	running	additional		or 4 sec	with: 0.4 sec
								engine starting	complete	-	-	complete	time if		cumulative	continuous
								fuel cut off modeled exhaust	TRUE <	750	° C	TRUE <750° C	fuel level is low and			or 4 sec cumulative
								temp	_	750	C	<750 C	is low and			cumulative
								in front of catalyst					not failed			
								A/F sensor heater	TRUE	-	-	TRUE				
								at operating temperature					600 sec			
Air / Fuel Ratio							l					1			l	
Air / Fuel Ratio Sensor (primary A/F)																
eneral error	P0130	general A/F sensor electrical fault	A/F sensor internal resistance	>	1500	Ohms	>1500Ohms	A/F sensor heater operation time	>	15	sec	>15sec	15 sec	0.1 sec	immediate	two driving
								fuel cut in time	>	15	sec	>15sec		continuous		cycles
								for a fuel cut off time	>	3	sec	>3sec				
								battery voltage	>	10.7	V	>10.7V				
								battery voltage	<	18	V	<18V				
								A/F sensor	ready			ready				
								A/F sensor heater pwr. stage err.	FALSE			FALSE				
								A/F sensor IC internal error	FALSE			FALSE				
								A/F sensor pin short circuit error	FALSE			FALSE				
								modeled exhaust gas temp. invalid	FALSE			FALSE				
								modeled exhaust gas temperature	>	0	°C	>0°C				
			calculated A/F sensor temperature	<	640	°C	<640°C	A/F sensor heater operation time	>	15	sec	>15sec	15 sec			
								fuel out in time		15	000	>15sec				
								fuel cut in time for a fuel cut off time	>	3	sec sec	>3sec				
								battery voltage	>	10.7	V	>10.7V				
								battery voltage	<	18	V	<18V				
								A/F sensor	ready			ready				
								A/F sensor heater pwr. stage err.	FALSE			FALSE				
								A/F sensor IC internal error	FALSE			FALSE				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								A/F sensor pin short circuit error	FALSE			FALSE				
								modeled exhaust gas temp. invalid	FALSE			FALSE				
								modeled exhaust gas temperature	>	0	°C	>0°C				
			A/F sensor pin UN error set	=	TRUE		=TRUE									
				=	TRUE		=TRUE									
			A/F sensor pin VM error set	=	TRUE		=TRUE									
			onor sec	=	TRUE		=TRUE									
			A/F sensor heater error set by	=	TRUE		=TRUE									
			after engine start diagnosis	=	TRUE		=TRUE									
			A/F sensor heater error set by	=	TRUE		=TRUE									
			maximum heater output diagnosis	=	TRUE		=TRUE									
r / Fuel Ratio ensor (primary (F)																
ference ground rcuit; reference oltage circuit; or easuring current rcuit																
ank 1 sensor 1 - w volt	P0131	A/F sensor signal at VM	IC Circuit Status shorted low	=	TRUE	-	=TRUE-	battery voltage	<	18	V	<18V	25 sec	0.1 sec	0.4 sec	two driving
ow voit		(reference ground) below lower limit						battery voltage	>	10.7	V	>10.7V		continuous	continuous	cycles each
		or A/F sensor signal at UN	IC Circuit Status shorted low	=	TRUE	-	=TRUE-	engine	running	-	-	running			or 4 sec	with: 0.4 se
		(reference voltage [Nernst voltage]) below lower limit	3					engine starting	complete	-	-	complete			cumulative	continuous
		or A/F sensor signal at IA	IC Circuit Status shorted low	=	TRUE	-	=TRUE-									or 4 sec
		(measuring current trim circuit) below lower limit														cumulative
ank 1 sensor 1 - gh volt	P0132	A/F sensor signal at VM	shorted high	=	TRUE	-	=TRUE-									
		(reference ground) above upper limi	it													
		or A/F sensor signal at UN	IC Circuit Status shorted high	=	TRUE	-	=TRUE-									

Component/	Fault	Monitor Strategy Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		(reference voltage [Nernst voltage]) above upper limit													
		or A/F sensor IC Circuit Status signal at IA shorted high	=	TRUE	-	=TRUE-									
		(measuring current trim circuit) above upper limit													
Air / Fuel Ratio Sensor (primary A/F)															
response		dynamic response A/F sensor dynamic value	<	0,2	ratio	< 0.2ratio	fuel trim forced amplitude	active	-	-	active				
Bank 1 Sensor 1	P0133	slow or low amplitude					A/F sensor	ready	-	-	ready	dynamic	0.01 sec	0.4 sec	two driving
					(versus	(versus	short term fuel trim (o.k.)	< MAX	1.25	factor	< MAX1.25factor	test	continuous	continuous	cycles each
					reference	reference	short term fuel trim (o.k.)	> MIN	0.75	factor	> MIN0.75factor	sample		or 4 sec	with: 0.4 sec
					sensor)	sensor)	measured A/F minus integral	<	1,05	lambda	<1.05lambda	count		cumulative	continuous
							control of secondary O2								or 4 sec
							measured A/F minus integral	>	0,95	lambda	>0.95lambda	>			cumulative
							control of secondary O2								
							engine speed	<	2800	rpm	<2800rpm	35			
							engine speed	>	1160	rpm	>1160rpm	samples			
							volumetric efficiency	<	45	%	<45%				
							volumetric efficiency	>	17.25	%	>17.25%	then			
							volumetric efficiency gradient	<	30	%/sec	<30%/sec	2 sec			
							A/F sensor housing model temp	<	570	°C	<570°C				
							filtered purge HC conc. factor	<	15	factor	<15factor	total time			
							or evap purge	not active			not active	= approx.			
							all fuel injectors active	TRUE			TRUE	600 sec			
							evap purge high HC conc.	FALSE	-	-	FALSE				
							A/F pumping current circuit	checked OK	-	-	checked OK				
							error: evap purge	not set	-	-	not set				
							error: evap purge valve circuit	not set	-	_	not set				
				_			scheduled by System Manager	TRUE	-	-	TRUE				
							forced amplitude	>	0.01	lambda	>0.01lambda				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Oxygen Sensor																
secondary O2)																
Frim of Air / Fuel Ratio Sensor																
(primary A/F)																
orimary A/F signal																
RICH / secondary																
O2 signal LEAN																
Bank 1	P2096	A/F sensor long	secondary O2	<	-0.03	lambda	<-0.03lambda	engine starting	complete	-	-	complete	2 sec	0.1 sec	0.4 sec	two driving
		term secondary	sensor trim													
		trim - rich shift	integral control					secondary O2 trim active	TRUE	-	-	TRUE		continuous	continuous	cycles each
		- correction below						and secondary	TRUE	-	-	TRUE			or 4 sec	with: 0.4 sec
		threshold						O2 oscillation								
								check finished		0.5		0.5			cumulative	continuous
primary A/F signal LEAN / secondary								then timer	>	25	sec	>25sec				or 4 sec
O2 signal RICH																
Bank 1	P2097	A/F sensor long term secondary	secondary O2 sensor trim	>	0.03	lambda	>0.03lambda	scheduled by System Manager	TRUE			TRUE				cumulative
		trim - lean shift	integral control					sec. O2 trim - fast	FALSE			FALSE				
			antogram commen					lean correction								
		- correction above						sec. O2 trim - fast	FALSE			FALSE				
		threshold						rich correction suspicion A/F	FALSE			FALSE				
								sensor lean shift	FALSE			FALSE				
								secondary O2	checked OK			checked OK				
								oscillation test								
Oxygen Sensor																
(secondary O2)																
Trim of Air / Fuel Ratio Sensor																
(primary A/F)																
Bank 1	P2195	secondary O2	secondary O2	>	0.75	V	>0.75V	A/F sensor	>	1.08008	lambda	>1.08008lambda	approx.	0.1 sec	0.4 sec	two driving
		sensor operation	sensor voltage					measured lambda								
		too rich - strong						short term fuel trim	= MAX	1.25	factor	= MAX1.25factor	100 sec	continuous	continuous	cycles each
		correction						Short term ruer trim	- IVIAX	1.25	lactor	= WAX1.25IdGl01	100 300	Continuous	Continuous	Cycles cacii
								A/F sensor	ready	-	-	ready			or 4 sec	with: 0.4 sec
		A/F sensor	or					secondary O2	ready	-	-	ready			cumulative	continuous
		measured too lean						sensor								
								then								or 4 sec
								accumulated	>	300	g	>300g				cumulative
								exhaust gas mass								
							0.751/	A/F sensor	>	1.08008	lambda	>1.08008lambda				
			secondary O2		0.75	V				1.00000	lambaa	>1.00000ambaa				
			secondary O2 sensor voltage	>	0.75	V	>0.75V	measured lambda								
				>	0.75	V	>0.75V	measured lambda								
				>	0.75	V	>0.75V	measured lambda secondary O2	>	0.014008	lambda	>0.014008lambda				
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim	>	0.014008	lambda	>0.014008lambda				
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim proportional trim dominating	>	0.014008	lambda	>0.014008lambda				
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim proportional trim dominating secondary O2	> complete	0.014008	lambda -	>0.014008lambda				
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim proportional trim dominating secondary O2 aging diagnosis	complete	-	-	complete				
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim proportional trim dominating secondary O2 aging diagnosis secondary O2								
				>	0.75	V	>0.75V	measured lambda secondary O2 sensor fuel trim proportional trim dominating secondary O2 aging diagnosis	complete	-	-	complete				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								A/F sensor	ready	-	-	ready				
								secondary O2	ready	-	-	ready				
								sensor								
								then accumulated	>	300		>300g				
								exhaust gas mass	,	300	g	>300g				
			secondary O2 sensor voltage	>	0.75	V	>0.75V	target lambda	>	1.04	lambda	>1.04lambda	0.9 sec			
			concer remage					A/F sensor	ready	-	-	ready				
								secondary O2	ready	-	-	ready				
								sensor								
								lambda closed	active	-	-	active				
								loop control								
								secondary O2 circuit diagnosis	complete	-	-	complete				
								short term fuel trim	> MIN	0.75	factor	> MIN0.75factor				
								(o.k.)		00	idoto.	r mintorrolación				
								then								
								accumulated	>	800	g	>800g				
								exhaust gas mass								
Oxygen Sensor																
secondary O2)																
Trim of Air / Fuel																
Ratio Sensor																
primary A/F)																
Bank 1	P2196	secondary O2 sensor operation	secondary O2 sensor voltage	<	0.2012	V	<0.2012V	A/F sensor measured lambda	<	0.92	lambda	<0.92lambda	approx.	0.1 sec	0.4 sec	two driving
			-					ale and to one five lattice	MINI	0.75	f	MINIO 7544	400		4:	
		too lean - strong correction						short term fuel trim	= MIN	0.75	factor	= MIN0.75factor	100 sec	continuous	continuous	cycles each
								A/F sensor	ready	-	-	ready			or 4 sec	with: 0.4 sec
		A/F sensor measured too rich						secondary O2 sensor	ready	-	-	ready			cumulative	continuous
								then								or 4 sec
								accumulated	>	300	g	>300g				cumulative
								exhaust gas mass	•		9					
			secondary O2	<	0.2012	V	<0.2012V	A/F sensor	<	0.92	lambda	<0.92lambda				
			sensor voltage					measured lambda								
								secondary O2	<	0.014	lambda	<0.014lambda				
								sensor fuel trim								
								proportional trim								
								dominating								
								secondary O2 aging diagnosis	complete	-	-	complete				
	·							secondary O2 circuit diagnosis	complete	-	-	complete				
								secondary O2 fuel trim active	TRUE	-	-	TRUE				
								A/F sensor	ready	-	-	ready				
								secondary O2	ready	-	-	ready				
								sensor				,				
_								then	_							
								accumulated exhaust gas mass	>	300	g	>300g				
								3gaoa30								
	-		secondary O2	<	0.2012	V	<0.2012V	target lambda	<	0.96	lambda	<0.96lambda	0.9 sec	1		

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								A/F sensor	ready	-	-	ready				
								secondary O2 sensor	ready	-	-	ready				
								lambda closed loop control	active	-	-	active				
								secondary O2 circuit diagnosis	complete	-	-	complete				
								short term fuel trim (o.k.)	< MAX	1.25	factor	< MAX1.25factor				
								then accumulated	>	800	g	>800g				
								exhaust gas mass		555	g	7 000g				
Air / Fuel Ratio																
Sensor (primary A/F)																
electrical vire to wire short circuit		sensor short to heater	filtered maximum pump current variation	>	0.00019	A	>0.00019A	all injectors activated	TRUE	-	-	TRUE	15 sec	0.01 sec	0.4 sec	two driving
oank 1 sensor 1	P2231		within every 10ms					battery voltage	<	18	V	<18V		continuous	continuous	cycles each
								battery voltage	>	10,7	V	>10.7V			or 4 sec	with: 0.4 sec
								A/F sensor IC diagnosis	complete	-	-	complete			cumulative	continuous
								error: A/F sensor IC	not set	-	-	not set				or 4 sec
								engine rpm	<	1800	rpm	<1800rpm				cumulative
								modeled exhaust gas temperature	<	800	°C	<800° C				
								heater duty cycle	>	20	%	>20%				
								heater duty cycle A/F sensor heater	< TRUE	80	%	<80% TRUE				
								at op.temp.	TRUE			TRUE				
								after A/F sensor curve switching								
								for time	>	0.06	sec	>0.06sec				
Diagnosis of Heater upstream HO2S																
1020	P0032	short circuit to battery voltage	Voltage	IC internal			IC internal	for time	>	5	sec	> 5 sec	5 sec	continous	0.2 sec	2 dcy
		,						battery voltage via main relay	<=	18	V	<= 18 V				
	P0031	short circiut to ground						battery voltage via main relay	>=	10,7	V	>= 10,7 V				
		giouna						condition end of	True			True				
	P0030	wire interruption						start condition engine	True			True				
								speed: n > NMIN								
A/F Sensor Heating																
neater performance (primary A/F)																

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
eank 1 sensor 1	P0135	A/F sensor calculated temperature	A/F sensor temperature calculation	<	715	° C	<715° C	battery voltage	>	10,7	V	>10.7V	35 sec	0.1 sec	0.4 sec	two driving
		too low						battery voltage	<	18	V	<18V		continuous	continuous	cycles each
								internal resistance measurement	valid	-	-	valid			or 4 sec	with: 0.4 sec
								all injectors activated	TRUE	-	-	TRUE			cumulative	continuous
								A/F sensor internal resistance	FALSE	-	-	FALSE				or 4 sec
								excessive correction required								cumulative
								engine stop time	>	5400	sec	>5400sec				
								engine temperature at start	>	-9,8	° C	>-9.8° C				
								A/F sensor heating ready	TRUE	-	-	TRUE				
								A/F heater control shut off	FALSE	-	-	FALSE				
								scheduled by System Manager	TRUE	-	-	TRUE				
neater performance primary A/F)																
pank 1 sensor 1 primary)	P0135	A/F sensor calculated	A/F sensor temperature calculation	<	715	° C	<715° C	A/F Heater at Maximum Power	TRUE			TRUE	60 sec	0.1 sec	0.4 sec	two driving
		temperature below threshold	,					modeled exhaust temp. at sensor	>	300	°C	>300° C		continuous	continuous	cycles each
								timer expires after either:	>	50	sec	>50sec			or 4 sec	with: 0.4 sec
								fuel shut off >= 3 sec dur. ends	-	-	-				cumulative	continuous
								or initial A/F heater turn on	-	-	-					or 4 sec
								battery voltage	>	10,7	V	>10.7V				cumulative
								battery voltage A/F heater control	FALSE	18	- V	<18V FALSE				
								shut off modeled exhaust temp. valid	TRUE			TRUE				
								scheduled by System Manager	TRUE	-	-	TRUE				
VF Sensor																
Heating																
neater performance (secondary O2)																
pank 1 sensor 1	P0053	correction value for A/F sensor	absolute value of correction value for	>	45	Ohms	>45Ohms	battery voltage	>	10.7	V	>10.7V	40 sec	0.1 sec	0.4 sec	two driving
pank 2 sensor 1		internal resistance measurement	A/F sensor internal resistance					battery voltage	<	18	V	<18V		continuous	continuous	cycles each
		too much						engine starting	complete	-	-	complete			or 4 sec	with: 0.4 sec
															cumulative	continuous

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
																or 4 sec cumulative
																ournaidi.vo
Oxygen Sensor sensor circuit																
(secondary O2)																
bank 1 sensor 2	P0137	short circuit to	secondary O2 sensor voltage	<	0.06	V	<0.06V	secondary O2 heating stable	>	10	sec	> 10sec	0.1 sec	0.1 sec	0.4 sec	two driving
		ground	sensor voltage					and mod. exhaust	>	250	° C	>250° C		continuous	continuous	cycles each
								gas temp.								
								for time	>	90	sec	>90sec			or 4 sec	with: 0.4 sec
								engine running	TRUE	-	-	TRUE			cumulative	continuous
								battery voltage	>	10.7	V	>10.7V				or 4 sec
								mod. exhaust-gas temp.	<	800	° C	<800° C				cumulative
								time after start	<	1	sec	<1sec				
								engine temp at	>	60	° C	>60° C				
								stop								
								engine temp	<	40	° C	<40° C				
								error: engine coolant temp	not set	-	-	not set				
bank 1 sensor 2	P0138	short circuit to	secondary O2	>	1.08	V	>1.08V	secondary O2	>	10	sec	> 10sec	5.1 sec			
Barik 1 delidel 2	1 0 100	battery voltage	sensor voltage >		1.00	•	×1.00 V	heating stable		10	500	7 10000	0.1 000			
								and mod.	>	250	°C	>250° C				
								Exhaust-gas temp.								
								for time	>	90	sec	>90sec				
								engine running	TRUE	-	-	TRUE				
								battery voltage	>	10.7	V	>10.7V				
								mod. exhaust-gas	<	800	° C	<800° C				
bank 1 sensor 2	P0140	sensor line	secondary O2	>	0.401	V	>0.401V	temp. secondary O2	>	10	sec	> 10sec	600 sec			
Darik i Serisor 2	F 0 140	disconnection	sensor voltage		0.401	V	20.40TV	heating stable		10	Sec	> 10360	000 360			
				<	0.499	V	<0.499V	and mod. Exhaust-	>	250	° C	>250° C				
			and secondary O2					gas temp.								
			sensor voltage					for time		90		>90sec				
			or					engine running	> TRUE	- 90	sec -	TRUE				
			secondary O2	>	40000	Ohm	>40000Ohm	battery voltage	>	10.7	V	>10.7V				
			sensor internal					James, ranaga								
			resistance													
			when modeled	>	600	° C	>600° C	mod. exhaust-gas	<	800	° C	<800° C				
			exhaust gas temperature					temp.								
			temperature													
Oxygen Sensor																
sensor circuit																
(secondary O2)	Doone	P 2 1	1 00					1 00		10		10	10	2.24	2.4	
bank 1 sensor 2	P2232	sensor line short circuit	secondary O2 sensor					secondary O2 heating stable	>	10	sec	> 10sec	10 sec	0.01 sec	0.4 sec	two driving
		to heater output	voltage gradient	>	2	V	>2V	and mod.	>	250	°C	>250° C		continuous	continuous	cycles each
		line	voltage gradient		_	•	724	Exhaust-gas temp.		200		7200 0		Continuous	Continuous	by old buon
			within time ofter		0.04	200	10.04000	for time		90	200	> 00000			or 4 000	with: 0.4 acc
			within time after heater turn off	<	0.04	sec	<0.04sec	for time	>	90	sec	>90sec			or 4 sec	with: 0.4 sec
			for occurrences	>	4	count	>4count	engine running	TRUE	-	-	TRUE			cumulative	continuous
			out of heater turn	=	6	count	=6count	battery voltage	>	10.7	V	>10.7V				or 4 sec
			offs					mod exhaust-gas		800	° C	<800° C				cumulative
								mod. exhaust-gas temp.	<	600		<000 C				cumulative
								time after dew	>	10	sec	>10sec				
								point exceeded			Ī				1	

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Oxygen Sensor Heating																
neater																
performance																
(secondary O2) bank 1 sensor 2	P0141	secondary O2	measured					battery voltage	>	10,7	V	>10.7V	6 sec	0.1 sec	0.4 sec	two driving
(secondary)	10141	sensor	secondary O2					battery voltage		10,7	v	>10.7 V	0 300	0.1 300	0.4 300	two driving
			sensor internal					1 0 1		40		40)/				
		internal resistance	resistance					battery voltage	<	18	V	<18V		continuous	continuous	cycles each
		above threshold	nominal internal	>	88 408	Ohms	>88 408Ohr	ns engine running	TRUE	-	-	TRUE			or 4 sec	with: 0.4 sec
			resistance		KFRINH		KFRINH	engine starting	complete	_	-	complete			cumulative	continuous
			multipy times	>	3 20	factor	>3 20facto		FALSE	-	-	FALSE			cumulative	or 4 sec
			degradation factor													
					FRINH		FRINH	sec. O2 internal	valid	-	_	valid				cumulative
								resistance	rana							oua.avo
			for time	>	6	sec	>6sec	intake air	>	-9,8	С	>-9.8C				
								temperature engine off soak	>	120	sec	>120sec				
								time								
								modeled exhaust temp.	in range	350 550	С	in range350 550C				
								at secondary O2				3300				
								sensor								
								suspicion of secondary	FALSE			FALSE				
								O2 sensor open								
								circuit								
								secondary O2 voltage supply	ON			ON				
								scheduled by								
								System Manager		400		400				
								for time	>	120	sec	>120sec				
sensor response																
(secondary O2) bank 1 sensor 2	P2270	oscillation check	secondary O2	<	0.499 0.603	V	<0.499 0.603	V secondary O2	ready	_	-	ready	approx.	0.1 sec	0.4 sec	two driving
5am 1 5511551 2	. 22.0	low	sensor voltage		0.100.11.0.000	•	10.1001110.000	sensor	·oaay			Today	арргож	0.1.000		the anning
			for time	>	5	sec	>5sec	for time	>	10	sec	>10sec	600 sec	continuous	continuous	cycles each
			then					secondary O2 closed loop control	active	-	-	active			or 4 sec	with: 0.4 sec
			ramping in	=	0.25	lambda	=0.25lambda	all injectors activated	TRUE	-	-	TRUE	additional		cumulative	continuous
			enrichment by at gradient	=	0.0513	I / sec	0,0513 I / sec		>	9.72	g/sec	9.72g/sec	time if			or 4 sec
							·	(intrusive test)								
			for time (after enrichment limit	>	7	sec	>7sec	and engine air flow	<	33.33	g/sec	33.33g/sec	fuel level			cumulative
			reached)					llow								
								for time	>	3	sec	>3sec	is low and			
								engine air flow (passive monitor)	>	9.72	g/sec	9.72g/sec	not failed			
								sec. O2 trim - fast lean correction	FALSE			FALSE	600 sec			
								sec. O2 trim - fast rich correction	FALSE			FALSE				
								engine	running			running				
								scheduled by	TRUE			TRUE				
								System Manager								

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
ank 1 sensor 2	P2271	oscillation check high	secondary O2 sensor voltage	>	0.499 0.603	V	>0.499 0.603	V secondary O2 sensor	ready	-	-	ready	approx.	0.1 sec	0.4 sec	two driving
			for time	>	5	sec	>5sec	for time	>	10	sec	>10sec	600 sec	continuous	continuous	cycles each
			then					secondary O2 closed loop control	active			active			or 4 sec	with: 0.4 sec
			ramping in enleanment by	=	0.07	lambda	=0.07lambda	all injectors activated	TRUE			TRUE			cumulative	continuous
			at gradient	=	0,0513	I / sec	0,0513 I / sec	engine air flow (intrusive test)	>	9.72	g/sec	9.72g/sec				or 4 sec
			for time (after enleanment limit reached)	>	7	sec	>7sec	and engine air flow	<	33.33	g/sec	33.33g/sec				cumulative
								for time	>	3	sec	>3sec				
								engine air flow (passive monitor)	>	9.72	g/sec	9.72g/sec				
								sec. O2 trim - fast lean correction	FALSE			FALSE				
								sec. O2 trim - fast rich correction	FALSE			FALSE				
								engine	running			running				
								scheduled by System Manager	TRUE			TRUE				
ank 1 sensor 2	P2271	fuel cut off check high	secondary O2 sensor voltage	>	0.202	V	>0.202V	secondary O2 heating stable	>	10	sec	> 10sec	0.2 sec	0.1 sec	0.4 sec	two driving
			time after fuel cut off	>	2,5	sec	>2,5sec	secondary O2 dew point exceeded	TRUE	-	-	TRUE		continuous	continuous	cycles each
								for time	>	30	sec	>30sec			or 4 sec	with: 0.4 sec
								air passed after fuel cut off	>	15	g	>15g			cumulative	continuous
								modeled exhaust temp	>	350	°C	>350° C				or 4 sec
								at secondary O2 sensor								cumulative
								scheduled by System Manager	TRUE	-	-	TRUE				
								error: cam sensor	not set	-	-	not set				
								error: evap canister purge sys.	not set	-	-	not set				
								error: evap purge valve ckt	not set	-	-	not set				
								error: battery voltage	not set	-	-	not set				
			_				_									
Camshaft Control System - Locking Pin																two driving
ank 1 Intake	P0011	rationality high	average of actual angle measurements	>	10	degrees	>10degrees	engine speed	>	560	rpm	>560rpm	10 sec	0.01 sec	0.4 sec	cycles each
Bank 2 Intake	P0021		versus locked position angle					engine run time	>	1	sec	>1sec			continuous	with: 0.4 sec
								camshaft control circuit test	complete	-	-	complete			or 4 sec	continuous
								error: camshaft control circuit	not set	-	-	not set			cumulative	or 4 sec cum
System - Control	P000A	rationality low / high	difference to start test (filtered actual	>	6	degrees	> 6degrees	engine speed	>	560	rpm	>560rpm	approx.	0.01 sec	0.4 sec	two driving

Component/	Fault	Monitor Strategy	y Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Bank 1 Intake	P000C		angle versus filtered desired angle)		KFDWNWDMXE /		KFDWNWDMXE 2	/ engine run time	>	1	sec	>1sec	20 sec	continuous	continuous	cycles each
Bank 2 Intake			(desired must remain above value					camshaft control circuit test	complete	-	-	complete			or 4 sec	with: 0.4 sec
			to test to complete the evaluation)					error: camshaft control circuit	not set	-	-	not set	(4 times		cumulative	continuous
			same as above, but offset added to the	+	0	degrees	+0degrees	coolant temperature	<	143	° C	< 143° C	for 4 sec			or 4 sec
			difference, during cold start only:					coolant temperature	>	-48	° C	>-48° C	each)			cumulative
			filtered actual angle remains	<			<	engine oil temperature	<	143	°C	<143° C				
			filtered desired angle from test start					engine oil temperature	>	-48	° C	>-48° C				
			within time	=	2	sec	=2sec	cam-crank alignment adaptation	complete	-	-	complete				
			(detects 5 sec slow [time constant])													
			for multiple activation occurrences	>	4	count	>4count									
			(decrements upon activations where				(same as stated i "time required" column)	n								
			no difference is seen between desired				,									
			and actual) same as above, but during cold start only:	>	2	count	>2count									
			difference (filtered actual angle max	>	3	degrees	>3degrees									
			versus actual at test start)													
			(to detect slow response versus stuck cam if above													
			this limit)													
			at time (overlaps with time to detect above)	=	4	sec	=4sec									
			(passes after multiple good activations													
			in both cam phase rotation directions)													
System - Cam -				-		-										
Crank Alignment																

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Bank 1 Intake	P0016	cam-crank adapted angle	adapted angle	>	18	degrees	>18degrees	engine run time >	>	2	sec	>2sec	approx.	0.2 sec	0.4 sec	two driving
		limit check	or adapted angle	<	-10	degrees	<-10degrees	engine coolant temp >	>	9.8	°C	>9.8° C	600 sec	continuous	continuous	cycles each
Bank 2 Intake	P0018	(applies for each camshaft)	or actual angle with parked cams	>	20	degrees	>20degrees	engine coolant temp <	<	105	°C	<105° C			or 4 sec	with: 0.4 sec
			and	<	25	degrees	<25degrees	model: engine oil temp <	<	140	°C	<140° C	fail after		cumulative	continuous
Bank 1 / Idler Sprocket	P0008		adapted angle for both cams	>	18	degrees	>18degrees	error: camshaft sensor	not set	-	-	not set	2 adaptation			or 4 sec
Bank 2 / Idler Sprocket	P0009		adapted angle for both cams	<	-10	degrees	<-10degrees	error: camshaft control circuit	not set	-	-	not set	cycles -			cumulative
													required			
Engine coolant	P0117	range check high	coolant temperature	>	138.8	°C	>138.8° C	hot restart timer after engine start	>=	60	sec	>=60sec	0.1 sec	0.1 sec	0.4 sec	two driving
emperature sensor	P0118	range check low	coolant temperature	<	-38.3	° C	<-38.3° C	If Startup ECT+O155	<	-38.3	° C	<-38.3° C			continuous	cycles each
								ECT-Startup ECT (abs value)	<=	2.3	°C	<=2.3° C			or 4 sec	with: 0.4 sec
								integrated air mass increases	>=	0	g	>=0g			cumulative	cont. or 4
								and air mass timer	>=	30	sec	>=30sec				sec cum.
	P0119	intermittent (discontinuity)	delta coolant temperature	<	-20.25	° C	<-20.25° C	ignition	=	ON		=ON	approx.	0.01 sec	immediate	
		discontinuity)	or										150 sec	continuous		
			delta coolant temperature	>	20.25	° C	>20.25° C									
			(between A/D read sample count offset)	=	3	count	=3count									
Engine coolant	P0116	plausibility check (low side check)	calculated coolant temperature model	>	9.8	°C	>9.8° C	the model temperature increases							or 0.4 sec	two driving
emperature sensor			minus measured temperature					depending on air flow							continuous	cycles each
		plausibility check (high side check)	measured temperature		9.8	° C		measured temperature	<	93.8	° C	<93.8° C				
			minus calculated coolant temperature model					engine speed	>	520	rpm	>520rpm			or 4 sec	with: 0.4 sec
								integrated air mass	>	3000	g	> 3000g			cumulative	continuous
								no error engine speed								or 4 sec
								no error air mass flow meter								cumulative
Engine coolant	P050C	difference from intake air	filtered difference					key up IAT - previous min IAT	<	1.5	° C	<1.5° C	160 sec	0.2 sec	immediate	two driving

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
emperature sensor		temperature after soaking	(ECT at key on - IAT at key on)	>	15	°C	>15° C	key up IAT - previous min IAT	>	-24.75	°C	>-24.75° C	for block	continuous	additional	cycles each
								previous accumulated air mass	>	2000	g	>2000g	heating		after block	with: 0.4 sec
								previous accumulated air mass	>	4000	g	>4000g			heater	cumulative
			or					previous engine run time	>	500	sec	>500sec			check	
			filtered difference					ECT at shut down	>	84.75	° C	>84.75° C				
			(ECT at key on - IAT at key on)	<	-10	°C	<-10° C	Controller Shut Down at end of	last cycle	-	-	last cycle				
								Strong Wind / Open Hood based on IAT rise	not detected	-	-	not detected				
								at shut down								
								Block Heater	not detected	-	-	not detected				
Engine Coolant	P0128	Coolant Temperature Below	(calculated reference model coolant temp	>	5.3	°C	>5.3° C	debouncing time	>	15	sec	>15sec	approx.	0.1 sec	0.4 sec	two driving
Thermostat Monitoring		Thermostat Regulating	minus measured coolant temperature)					error: engine coolant temp	not set	-	-	not set	900 sec	continuous	continuous	cycles each
		Temperature (plausibility check)						error: vehicle speed sensor	not set	-	-	not set			or 4 sec	with: 0.4 sec
			reference model calculation limit		74,3 75,8	°C	74,3 75.8° C	est. ambient temperature	>	-39.8	°C	> -39.8°C			cumulative	continuous
								est. ambient temperature	<	140	°C	<140°C				or 4 sec
			(development vehicles indicated					vehicle speed	>=	3.125	mph	>=3.125mph				cumulative
			steady thermostat regulating					engine speed	>	640	rpm	>640rpm				
			temperatures of 89°C, as measured					coolant temperature at start	<	69.8	°C	< 69.8°C				
			by the engine coolant temp. sensor.					integrated air mass flow	>	1000	g	> 1000g				
			The thermostat opening temp.													
			is 82°C. The thermostat is fully open													
			by 95°C. All critical OBD and													
			emission functions are enabled													
			above 60°C.)													
ntake air emperature	P0111	response check	max intake air temperature -					drive period - count	>=	5	count	>=5count	2 sec	0.1 sec	0.4 sec	two driving
sensor			min intake air temperature	>	2.3	°C	>2.3° C	each with						continuous	continuous	cycles each

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								vehicle speed	>=	56.25	mph	>=56.25mph			or 4 sec	with: 0.4 sec
								mass flow	<	250	g/sec	<250g / sec			cumulative	continuous
								mass flow	>	25.6	g/sec	> 25.6g/sec				or 4 sec
								coolant	<=	120	°C	<=120° C				cumulative
								temperature at								
								start								
								no fuel shut-off								
								idle period - count	>=	4	count	>=4count				
								each with								
								vehicle speed	<=	1.5625	mph	<=1.5625mph				
								coolant	<=	120	°C	<=120° C				
								temperature at								
								start								
								coolant	>	64.5	°C	>64.5° C				
								temperature								
								ECT decrease	>	0	°C	>0° C				
								since prior								
								shutdown								
	P0112	range check low	intake air	>	125.3	° C	>125.3° C									
			temperature													
	P0113	range check high	intake air	<	-35.3	° C	<-35.3° C	time after start	>	15	sec	> 15sec				
			temperature													
								then time in idle	>	3	sec	>3sec				
								and intake air	<	-35.3	°C	<-35.3° C				
								temperature								
								then IAT change	<=	2.3	°C	<=2.3° C				
								(abs value)								
								while								
								integrated air mass	>=	0	g	>=0g				
								increases								
Mass air flow	P0101	range check low	mass air flow		1.83 78.9	g/sec	-1.93 79.0	battery voltage		10.5	V	>10.5V	0.40 sec	0.01 sec	0.4 sec	two driving
ensor	PUIUI	range check low	IIId55 dil IIUW	<	1.03 10.9	g/sec	g/sec	battery voltage	>	10.5	v	>10.50	0.40 Sec	0.01 Sec	0.4 Sec	two unving
elisui		or	and		KFMLDMN		KFMLDMN	time after start	>	0.4	sec	>0.4sec		continuous	continuous	cycles each
		fuel trim limits	delta lambda		0,16	factor	>0.16factor	crankshaft		150		>0.4sec >150rev		Continuous	or 4 sec	with: 0.4 sec
		exceded	correction	>	0,16	ractor	>0.16180101	revolution counter	>	150	rev	>150feV			Of 4 Sec	with: 0.4 Sec
		exceded	Correction					revolution counter								
		range -						error: throttle	not set	-	-	not set			cumulative	continuous
		multiplicative						position sensor	not set	-	_	1101 361			Cumulative	Continuous
		and						position sensor		0	0	00				or 4 sec
																cumulative
			correction factor air		0.83	factor	<0.83factor			0	a/c					Cumulative
		correction factor	correction factor air	<	0.83	factor	<0.83factor			0	g/s	0g/s				
		correction factor (modeled air	correction factor air mass	<	0.83	factor	<0.83factor	ratio: MAP to Raro								
		correction factor (modeled air mass at throttle /		<	0.83	factor	<0.83factor	ratio: MAP to Baro	<	1	g/s -	0g/s <1 -				
		correction factor (modeled air mass at throttle / air mass		<	0.83	factor	<0.83factor			1	-					
		correction factor (modeled air mass at throttle / air mass measured by air		<	0.83	factor	<0.83factor	ratio: MAP to Baro	< >							
		correction factor (modeled air mass at throttle / air mass		<	0.83	factor	<0.83factor	air mass flow	>	1 8.3	- g/sec					
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter)	mass					air mass flow time after start	>	1	-					
		correction factor (modeled air mass at throttle / air mass measured by air	mass	>	0.83 26.9 312.5	factor	> 26.9 312.	air mass flow time after start	>	1 8.3	- g/sec					
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter)	mass air flow		26.9 312.5		> 26.9 312. g/sec	air mass flow time after start ferrors:	>	1 8.3	- g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high	mass air flow	>	26.9 312.5 KFMLDMX	g/sec	> 26.9 312. g/sec KFMLDMX	air mass flow time after start errors: throttle body	>	1 8.3	- g/sec					
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits	mass air flow and delta lambda		26.9 312.5		> 26.9 312. g/sec	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits exceded	mass air flow	>	26.9 312.5 KFMLDMX	g/sec	> 26.9 312. g/sec KFMLDMX	air mass flow time after start errors: throttle body	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits exceded range -	mass air flow and delta lambda	>	26.9 312.5 KFMLDMX	g/sec	> 26.9 312. g/sec KFMLDMX	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits exceded range - multiplicative	mass air flow and delta lambda	>	26.9 312.5 KFMLDMX	g/sec	> 26.9 312. g/sec KFMLDMX	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits exceded range - multiplicative and	mass air flow and delta lambda correction	>	26.9 312.5 KFMLDMX -0.175	g/sec factor	> 26.9 312. g/sec KFMLDMX <-0.175factor	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass at saured by air mass flow meter) range check high or fuel trim limits exceded range - multiplicative and correction factor	mass air flow and delta lambda correction correction factor air	>	26.9 312.5 KFMLDMX	g/sec	> 26.9 312. g/sec KFMLDMX	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				
		correction factor (modeled air mass at throttle / air mass measured by air mass flow meter) range check high or fuel trim limits exceded range - multiplicative and	mass air flow and delta lambda correction	>	26.9 312.5 KFMLDMX -0.175	g/sec factor	> 26.9 312. g/sec KFMLDMX <-0.175factor	air mass flow time after start ferrors: throttle body Leak upstream	>	1 8.3 1	g/sec	<1-				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		measured by air mass flow meter)														
	P0102	circuit check low	mass air flow	<	-10.3	g/sec	>10.3g/sec	battery voltage	>	7.5	V	>7.5V	0.2 sec			
	P0103	circuit check high	mass air flow	>	333.3	g/sec	>33.3g/sec									
						J. T. T.										
pressure sensor	Dooon	-1-4144114			4.05		4.05.1/						0.5		0.0	0 1
upstream throttle valve	P0238	cirtcuit continuity - high or open	voltage	>	4.65	V	> 4.65 V						0.5 sec	continuous	0.2 sec	2 dcy
	P0237	cirtcuit continuity - low	measured sensor voltage	<	0.45	V	< 0.45 V									
	Doogo	and the second state			200	LD-	200 I-D-	a a a la la al la co					0			
	P0238	range check - high	measured pressure	>	300	kPa	> 300 kPa	enabled by diagnostic					2 sec			
	P0237	range check - low	measured pressure	<	50	kPa	< 50 kPa	scheduler	true			true				
-	P0236	rationality -														
		,	measured fuel pressure lies below													
		comparison	procedure neer pereur	true			true									-
		between measured	d expected minimum pressure													
		pressure and expected														
		(calculated) pressure														
		pressure														
	P0236	rationality -	('measured') compression ratio exceeds													
		comparison		true			true									
		between ('measured')	expected maximum													
		compression ratio	compression ratio													
		compression rational and expected														
		(calculated)														
		compression ratio														
boost pressure																
control	P2281	comparison	ratio between	>	0.098		> 0.098	engine speed	>	1520	rpm	> 1520 rpm	1 sec	continuous	0.2 sec	2 dcy
		between MAF based	MAF based		to		to	time after engine	>	10	sec	> 10 sec				
		pressure ratio	pressure ratio					start								
		over the throttle valve	over the throttle valve		1.25		1.25	no fault of								
		and	and					- pressure sensor								
		throttle body	throttle body based					upstream	true			true				
		based pressure ratio	pressure ratio					throttle valve								
		over the throttle valve	over the throttle valve					- throttle position sensors	true			true				
		vaive	valVe					- MAF sensor	true			true				
		(detection of	(fine leakage)					boost pressure								
		leakage)						control								

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								is active	true			true				
			ratio between	>	0.101		> 0.101						1 sec			
			MAF based	-	to		to									
			pressure ratio													
			over the throttle valve		1.297		1.297									
			and													
			throttle body based													
			pressure ratio													
			over the throttle													
			valve													
			(coarse leakage)													
			ratio between	>	0.109		> 0.109	engine speed	>	1520	rpm	> 1520 rpm	1.8 sec			
			MAF based pressure ratio		to		to	time after engine start	>	10	sec	> 10 sec				
			over the throttle		1.398		1.398	no fault of								
			valve													
								- pressure sensor								
			and throttle body based					upstream	true			true				
			pressure ratio					throttle valve	udo			ui do				
			over the throttle valve					- throttle position sensors	true			true				
								- MAF sensor	true			true				
			(coarse leakage)					- canister purge system	true			true				
								boost pressure control								
								is not active	true			true				
								for time	>			>				
								cruise control not active	true			true				
								setpoint canister	<	0.03		< 0.03				
								purge rate								
								no dynamic engine condition	true							
	P0299	comparison between	difference (positive)	>	12	kPa	> 12 kPa	boost pressure control					6 sec			
		desired boost	between set-point boost					is active	true			true				
		pressure and	pressure and					engine speed	>	2000	rpm	> 2000 rpm				
		current boost	current boost					engine speed		or	трпп	or				
		pressure	pressure													
										2800	rpm	2800 rpm				
			(boost pressure to low)					atmospheric pressure	>	66	kPa	> 66 kPa				
T								setpoint boost pressure	>	base		> base			T	
								prossure		boost		boost				
										pressure		pressure				
										+		+				
										5	kPa	5 kPa				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0234	comparison between	difference (negative)	>	32	kPa	> 32 kPa	pressure upstream throttle					0.8 sec			
		desired boost pressure	set-point boost pressure		to		to	valve is valid	true			true				
		and	and		127.5	kPa	127.5 kPa									
		current boost pressure	current boost pressure													
			(boost pressure to high)													
			(Remark: for comparison the negative													
			value is converted to an absolute value)													
dump valve	P2261	counting of	normalized					engine coolant	>	50.3	°C	> 50.3 °C	0.48 sec	continuous	0.2 sec	2 dcy
		increased pulsation	difference between					temperature								
		in the intake manifold	measured MAF sensor value and					intake air temperature	>	-10.5	°C	> -10.5 °C				
			modeled value	>	0,352		> 0,352	pressure in front of								
		(increased pulsation may occure						throttle valve	>	60	kPa	> 60 kPa				
		when dump valve is jammed						supervision phase is active	true			true				
		in closed position)													
			number of times	>	4	counts	> 4 counts	conditions for an active								
								supervision phase are								
								 negative load gradient 								
								detected	true			true				
								- ratio of pressure in front of	>	1.05		> 1.05				
								throttle valve to minimum		to		to				
								pressure after air filter		3.12		3.12				
								- dump valve is active	true			true				
Barometric Pressure Sensor	P2227	rationality	difference between barometric pressure										3 sec	0.1 sec	0.4 sec	two driving
(ambient air pressure sensor)		signal discontinuity	signal pressure and pressure in front of throttle	>	15	kPa	>15kPa	plausible pressure signal pressure sensor	TRUE			TRUE			continuous	cycles each
								in front of throttle							or 4 sec	with: 0.4 sec
								and							cumulative	continuous

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								throttle angle	<	5	%	<5%				or 4 sec
								and engine speed	<	1000	rpm	<1000rpm				cumulative
			or					enabled by scheduler for time	>	3	sec	>3sec				
			barometric pressure signal pressure													
			jump from previous key off	>	10	kPa	>10kPa	Baro from previous drive	valid	-	-	valid				
								difference: Baro substitute	>	15	kPa	>15kPa				
			and					model versus sensor								
								engine speed lower	<	621	rpm	< 621 rpm				
			difference between barometric pressure	>	10	kPa	>10kPa	and								
			signal pressure and pressure in front of throttle					throttle angle	<	5	%	< 5%				
			unotuo					both for time	>	3	sec	>3sec				
	P2228	range check low	sensor signal	<	45	kPa	<45kPa	enabled by scheduler for time	>	1	sec	>1sec	2 sec			
			sensor voltage	<	0.45	V	< 0,45V						0.5 sec			
	P2229	range check high	sensor signal	>	115	kPa	>115kPa	enabled by scheduler for time	>	1	sec	>1sec	2 sec			
			sensor voltage	>	4.8	V	>4,8V						0.5 sec			
Idle Speed System																
(disabled during cold start)	P0506	functional check	desired rpm - actual rpm	>	100	rpm	>100rpm	load (for underspeed only)	<	39.75	%	<39.75%	10 sec	0.1 sec	0.4 sec	two driving
								coolant temp.	>	64.5	° C	>64.5° C		continuous	continuous	cycles each
	P0507		desired rpm - actual rpm	<	-200	rpm	<-200rpm	intake air temp	>	-10.5	°C	>-10.5° C			or 4 sec	with: 0.4 sec
			or fuel cut off due to overspeed	>	3	count	>3count	vehicle altitude factor (sea level = 1.0)	at idle >	0.703	factor	at idle >0.703factor			cumulative	continuous or 4 sec
			during this idle					time after engine	>	0	sec	>0sec				cumulative
								cold start idle speed control	FALSE			FALSE				
								intrusive evap test	not active			not active				
Idle Speed System																
(enabled during cold start)	P0506	functional check	desired rpm - actual rpm	>	100	rpm	>100rpm	load (for underspeed only)	<	39.75	%	<39.75%	5 sec	0.1 sec	0.4 sec	two driving

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
			during catalyst heating on					Engine coolant start temp.	>	-10 +40	°C	> -10 +40° C		continuous	continuous	cycles each
	P0507		desired rpm - actual rpm	<	-200	rpm	<-200rpm	intake air temp	>	40	° C	>40° C			or 4 sec	with: 0.4 sec
			during catalyst heating on			<u> </u>		vehicle	at idle			at idle			cumulative	continuous
								altitude factor (sea level = 1.0)	>	0.703	factor	>0.703factor				or 4 sec
								time after engine	>	0	sec	>0sec				cumulative
								idle speed control catalyst heating	TRUE			TRUE				
						 		intrusive evap test	not active			not active				
ehicle speed																
ensor	P0500	rationality	vehicle speed	>	171.875	mph	>171.875mph	-	-	-	-		2 sec	0.1 sec	0.4 sec	two driving
		(high range check)				<u> </u>								continuous	continuous	with: 0.4 sec
		rationality	vehicle speed minus	=	0	mph	=0mph	vehicle speed	>	0	mph	>0mph			or 4 sec	continuous
		(stuck check)	previous vehicle speed					vehicle speed	<	319.375	mph	<319.375mph			cumulative	or 4 sec
			opecu			 [time	>	10	sec	>10sec				cumulative
		CAN wheel speed message check	CAN wheel speed message corrupt	=	corrupt		=corrupt									
			or missing	=	missing		=missing									
Crankshaft Position Sensor	P0335	circuit continuity	no engine signal	=	0	rpm	=0rpm	camshaft revolutions detected	>	12	counts	>12counts	арргох.	0.01 sec	0.4 sec	two driving
			but phase signals available					detected					5 sec	continuous	continuous	cycles each
		rationality check	,	>		gaps									4	with: 0.4 sec
			reference gap		6	gaps	>6gaps								or 4 sec	
			missing (sensor signal but no reference)		6	gaps	>6gaps								cumulative	continuous
	P0336	rationality check	missing (sensor signal but no reference) unexpected re-	>	6	count	>6gaps									continuous or 4 sec
	P0336	rationality check	missing (sensor signal but no reference)													
	P0336	rationality check	missing (sensor signal but no reference) unexpected resynchronization (loss of reference													or 4 sec
	P0336		missing (sensor signal but no reference) unexpected re- synchronization (loss of reference mark) intermittent loss of	>	6	count	>6count						арргох.	1 per rev		or 4 sec
		rationality check	missing (sensor signal but no reference) unexpected re- synchronization (loss of reference mark) intermittent loss of engine speed signal difference in counted	>	6	count	>6count >14count						approx.	1 per rev		or 4 sec
:amshaft Position		rationality check	missing (sensor signal but no reference) unexpected re- synchronization (loss of reference mark) intermittent loss of engine speed signal difference in counted teeth between reference gap	>	6	count	>6count >14count							·		or 4 sec
camshaft Position tensor ank 1 Intake		rationality check	missing (sensor signal but no reference) unexpected re- synchronization (loss of reference mark) intermittent loss of engine speed signal difference in counted teeth between reference gap position events	>	6 14	count	>6count >14count	engine in synchronized mode	TRUE	-	-	TRUE		·		or 4 sec

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0343	circuit continuity or high		>			>								or 4 sec	with: 0.4 sec
															cumulative	continuous
Bank 2 Intake	P0345	plausibility check		>	5	count	>5count								cumulative	or 4 sec
	P0347	circuit low	sensor signal	>	5	count	>5count									cumulative
	P0348	circuit continuity or high		>	5	count	>5count									
fuel tank pressure sensor								barometric pressure	>=	68	kPa	>= 68 kPa	14 sec	continous	0.4 sec	2 dcy
	P0453	circuit continuity - high or open	fuel tank pressure	>	3781	Pa	> 3781 Pa	vehicle speed	=	0	mph	= 0 mph				
								fuel level fuel level	> <	6,2 87	%	> 6,2 % < 87 %				
	P0452	circuit continuity -	fuel tank pressure	<	-4000	Pa	< -4000 Pa	engine start finished	true	01	70	true				
								enabled by diagnostic scheduler	true			true				
_	P0451	rationality -	fuel tank pressure					Scriedulei								
			difference	>=	813	Pa	>= 813 Pa						25.5 sec	continous	0.4 sec	2 dcy
		sensor signal change within time	within	=	1	sec	= 1 sec	canister vent valve open	true			true				
		(oscillation check)	for integrated time	>=	25.5	sec	>= 25.5 sec	for time	>	3	sec	> 3 sec				
								vehicle speed	<=	18.64	mph	<= 18.64 mph				
								enabled by diagnostic scheduler	true			true				
	P0451		max-min difference					vehicle speed								
		signal stuck (incremental check)	of canister purge valve duty cycle	>=	39.84	%	>= 39.84 %		>=	6.22	mph	>= 6.22 mph	25 sec	continous	0.4 sec	2 dcy
			and					canister purge is active	true			true				
			max-min difference of fuel tank pressure signal	<	80	Pa	< 80 Pa	ratio of intake manifold pressure to atmospheric pressure	<=	0.477	-	<= 0.477 -				
			for number of	>=	2	counts	>= 2 counts	atmospheric	>=	00		>= 68 kPa				
			checks					pressure incremental check without result yet	true	68	kPa	true				
								fuel level	>	6,2	%	> 6,2 %				
								fuel level enabled by	< true	87	%	< 87 %				
								diagnostic scheduler	uue			true				
	P0327	Monitoring via knock-sensor- and	Cylinder individual signal value	<	0.7422 6.8164	V	< 0.7422 6.816	64 - Knock control is active.	true			true	0,3 sec	continuous	2.6 sec	no MIL

Component/	Fault		Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		cylinder-based basic reference noise	(depends on engine speed)					- engine coolant tempetature	>	45	°C	> 45 °C				
	P0328	signal (voltage).	Cylinder individual signal value	>	57.8908 72.7541	V	> 57.8908 72.7541 V	- load	>	30	%	> 30 %				
			(depends on engine speed)					- Engine speed for strong signals.	>	2520	rpm	> 2520 rpm				
								- Engine speed for weak signals.	>	2520	rpm	> 2520 rpm				
								- No phase sensor faults during	true			true				
								engine start.								
								- Engine speed dynamics for	false			false				
								knock detection								
								exist.	false			folos				
								- Load dynamics for knock	laise			false				
								detection exist.								
								- No ECM knock-	true			true				
								control ciruit								
								error Engine stpeed	false			false				
								limp home	laise			iaise				
								function is active.								
	P0332	Monitoring via knock-sensor- and	Cylinder individual	<	0.7422 6.8164	V	< 0.7422 6.8164 V	- Knock control is active.	true			true	0,3 sec	continuous	2.6 sec	no MIL
		KIIOCK-SEIISOI- AIIU	signal value				v	active.								
		cylinder-based basic reference noise	(depends on engine speed)					- engine coolant tempetature	>	45	°C	> 45 °C				
	P0333	signal (voltage).	Cylinder individual signal value	>	57.8908 72.7541	V	> 57.8908 72.7541 V	- load	>	30	%	> 30 %				
			(depends on engine speed)					- Engine speed for strong signals.	>	2520	rpm	> 2520 rpm				
								- Engine speed for weak signals	>	2520	rpm	> 2520 rpm				
								- No phase sensor faults during	true			true				
		1						engine start.								
								- Engine speed	false			false				
								dynamics for knock detection								
								exist.								
								- Load dynamics for knock	false			false				
								detection exist.	Amus			Aur				
								- No ECM knock- control ciruit	true			true				
								error.								
								- Engine speed limp home	false			false				
																1

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Knock control sensor's evaluation IC													250 working	Zero and	2.6 s	2 dcy
		Response to Zero Pulse											cylces	Test pulse		
	P0324	monitor IC's integrator offset	integrator's value - 715mV	>	0.215	V	> 0.215 V	knock control active	true	-	-	true		alternate every		
								no dynamic condition on engine speed	true	-	-	true		250 working		
								no dynamic condition on engine load	true	-	-	true		cycles.		
								no fault assumption from knock control								
								test pulse.	true	-	-	true				
								the engine speed is within a calibrated								
								range	true	-	-	true				
	P0324	monitor IC's integrator gradient	integrator gradient	>	measuring window length dependent	V/s		same as for IC integrator's offset monitoring								
		Response to Test Pulse														
	P0324	integrator value check	integrator value of test pulse	<	3.691	V	< 3.691 V	the engine coolant temperature > calibration	true			true				
								no dynamic condition on engine speed	true			true				
								no dynamic condition on engine load	true			true				
								no fault assumption from the knock								
								control zero test.	true			true				
Transmission Control Module	P0700	OBD emission fault	signal input	=	TCM MIL	FAULT	=TCM MILFAUL	Т -	-	-	-		0.01 sec	0.01 sec	immediate	immediate
MIL Illumination Request		detected by the TCM												continuous		
	(Specific TCM DTC shown in freeze frame)															
fuel injector										1						
fuel injector cylinder #1	P0201	circuit continuity -	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
	P0261	circuit continuity - ground						battery voltage	>	9,99	V	> 9,99 V				
	P0262	circuit continuity - voltage						battery voltage	<	17,99	V	< 17,99 V				
cylinder #2	P0202	circuit continuity - open						output activated and								
	P0264	circuit continuity - ground						deactivated for complete								

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0265	circuit continuity -						checking	true			true				
cylinder #3	P0203	voltage circuit continuity -														
•	D0007	open														
	P0267	circuit continuity - ground														
	P0268	circuit continuity -														
cylinder #4	P0204	voltage circuit continuity -														
-,		open														
	P0270	circuit continuity - ground														
	P0271	circuit continuity -														
cylinder #5	P0205	voltage circuit continuity -														
dymidel no		open														
	P0273	circuit continuity -														
	P0274	ground circuit continuity -														
audia da s #C	Doone	voltage														
cylinder #6	P0206	circuit continuity - open														
	P0276	circuit continuity -														
	P0277	ground circuit continuity -														
		voltage														
	50110		14.5	101			10.1									
canister ventilation valve	P0449	circuit continuity - open	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
	P0498	circuit continuity -						battery voltage	>	9,99	V	> 9,99 V				
	P0499	ground circuit continuity -						battery voltage	<	17,99	V	< 17,99 V				
		voltage							-	,		,				
								output activated and								
								deactivated for								
								complete checking	true			true				
								oo								
canister purge	P0443	circuit continuity -	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
valve	P0458	open circuit continuity -						battery voltage	>	9,99	V	> 9,99 V				
		ground														
	P0459	circuit continuity - voltage						battery voltage	<	17,99	V	< 17,99 V				
		voltage						output activated								
								and								
								deactivated for complete								
								checking	true			true				
downstroam					1											
downstream oxygen sensor																
haatar				IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
heater Bank #1	P0036	circuit continuity -														

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0037	circuit continuity - ground						battery voltage	>	9,99	V	> 9,99 V				
	P0038	circuit continuity -						battery voltage	<	17,99	V	< 17,99 V				
		voltage						output activated								
								and deactivated for								
								complete checking	true			true				
aandan, sir	D0449	circuit continuity -	Voltage	IC internal			IC internal	angina angad		00	W0 00	. 00 ***	inomo di atalu	aantinuuus	0.2.000	O day
econdary air ump	P0418	open	vollage	ic internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
	P2445	circuit continuity - ground						battery voltage	>	9,99	V	> 9,99 V				
	P2444	circuit continuity - voltage						battery voltage	<	17,99	V	< 17,99 V				
		voltage						output activated and								
								deactivated for								
								complete checking	true			true				
								, and the second								
ntake camshaft control																
ntake Bank #1	P0010	circuit continuity - open	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	2 dcy
	P2088	circuit continuity -						battery voltage	>	9,99	V	> 9,99 V				
	P2089	ground circuit continuity -						battery voltage	<	17,99	V	< 17,99 V				
ntake Bank #2	P0020	voltage circuit continuity -						output activated								
	P2092	open circuit continuity -						and deactivated for								
		ground						complete								
	P2093	circuit continuity - voltage						checking	true			true				
ump valve turbo	P0033	circuit continuity -	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	no MIL
p 0 tai 20	P0034	open circuit continuity -	9-					battery voltage	>	9,99	V	> 9,99 V			5.2 555	
		ground						, ,								
	P0035	circuit continuity - voltage						battery voltage	<	17,99	V	< 17,99 V				
								output activated and								
								deactivated for								
								complete checking	true			true				
oost control valve	P0244	circuit continuity -	Voltage	IC internal			IC internal	engine speed	>	80	rpm	> 80 rpm	immediately	continuous	0.2 sec	no MIL
	P0245	open circuit continuity -						battery voltage	>	9,99	V	> 9,99 V	-			
		ground														
	P0246	circuit continuity - voltage						battery voltage	<	17,99	V	< 17,99 V				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								output activated								
								and								
								deactivated for complete								
								checking	true			true				
Ignition Coil																
circuit continuity	P0351	airquit aantinuity			20	rovo	> 20rovo	angina angad		600	rom	- 600rpm	annray	ongino	0.4 sec	two driving
Cylinder #1	F0331	circuit continuity - open or signal not plausible	Voltage > during		20	revs	>20revs	engine speed	>	800	rpm	>600rpm	approx.	engine	0.4 560	two driving
		piddolbic	or minimum two fault	>	3			engine speed	<	5000	rpm	<5000rpm	1 sec	cycle	continuous	cycles each
			counters					3 - 1			· ·					.,
	P2300	circuit continuity -			20	revs	>20revs	battery voltage	>	10	V	>10V		frequency	or 4 sec	with: 0.4 sec
	D2201	ground	Voltage > during		20	rovo	> 20rovo	hottory voltage		18	V	-10\/			oumulativo	continuous
	P2301	circuit continuity - voltage	Voltage > during		20	revs	>20revs	battery voltage	<	10	v	<18V			cumulative	continuous
Cylinder #2	P0352	circuit continuity -			20	revs	>20revs							continuous		or 4 sec
		open or signal not														
		plausible	Voltage > during													1.0
			or minimum two fault counters	>	3											cumulative
	P2303	circuit continuity -	counters		20	revs	>20revs									
	. 2000	ground	Voltage > during			1010	720.010									
	P2304	circuit continuity -			20	revs	>20revs									
		voltage	Voltage > during													
Cylinder #3	P0353	circuit continuity -	Voltage > during		20	revs	>20revs									
		open	or minimum two fault	>	3											
			counters													
	P2306	circuit continuity -			20	revs	>20revs									
		ground	Voltage > during													
	P2307	circuit continuity -	Voltage > during		20	revs	>20revs									
Cylinder #4	P0354	voltage circuit continuity -	Voltage > during		20	revs	>20revs									
		open	Voltage > during													
			or minimum two fault	>	3											
			counters													
	P2309	circuit continuity - ground	Voltage > during		20	revs	>20revs									
	P2310	circuit continuity -	voltage > during		20	revs	>20revs									
		voltage	Voltage > during													
Cylinder #5	P0355	circuit continuity -			20	revs	>20revs									
		open	Voltage > during		3											
			or minimum two fault counters	>	3											
	P2312	circuit continuity -			20	revs	>20revs									
		ground	Voltage > during													
	P2313	circuit continuity -	Valtage during		20	revs	>20revs									
Cylinder #6	P0356	voltage circuit continuity -	Voltage > during		20	revs	>20revs						+			
Symidol #0	. 5556	open	Voltage > during		20	1043	2201643									
		·	or minimum two fault	>	3											
	D02:-		counters				0.5									
	P2315	circuit continuity - ground	Voltage > during		20	revs	>20revs									
	P2316	circuit continuity -	voltage > during		20	revs	>20revs						+			
		voltage	Voltage > during													
					_								_			
Electronic Throttle																
Control	P0638	motor control	powerstage duty	>	80	%	>80%	battery voltage	_	7	V	>7V	0.6 sec	0.01 sec	immediate	immediate
	F 0030	range check	cycle	_	30	70	>00 70	battery voltage	>	′	v	-/ V	0.0 Sec	0.01 566	minieulate	mmediale

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
		short term	(absolute value)	>	80	%	>80%						(recoverable)	continuous		
		motor control											5.0 sec			
		range check														
		long term											(latched)			
ectronic Throttle																
ontrol	P1551	East bear threathe	4		4.0000	0/	4.00000/			0		0h	5	0.04	income aliente	in a dista
	P1551	limp-home throttle position	throttle position	<	1.8006	%	<1.8006%	vehicle speed	<=	0	mph	<=0mph	5 sec	0.01 sec	immediate	immediate
		out of range	OR					engine speed	<	40	rpm	<40rpm		at key on		
			throttle position	>	13.0785	%	>13.0785%	engine coolant temperature	>=	5.25	° C	>=5.25° C				
								engine coolant	<=	84.75	° C	<=84.75° C				
								temperature intake air	>=	5.25	°C	>=5.25° C				
								temperature	/-	3.23		>=3.23 0				
								intake air	<=	60	° C	<=60° C				
-								temperature battery voltage	>	9.99	V	>9.99V				
								accelerator pedal	<	14.9	%	<14.9%				
								position								
ectronic Throttle																
ontrol	P2100	noworotogo oirouit	output airquita not		deactivation	fault	=deactivationfaul			_	_		0.1 sec	0.01 sec	immediate	immediate
	P2100	switch-off	output circuits not deactivated	=	deactivation	lault	=ueaciivaiioiiiaui	. -	-	-	-		0.1 Sec	0.01 Sec	immediate	immediate
			as commanded											at key on		
	P2101		difference between	>	4 50	%	>4 50%	electronic throttle	not active	-	-	not active	0.5 sec	0.01 sec	immediate	immediate
		set and actual position of	set and actual position of		dep. on rate of		dep. on rate of	adaptation battery voltage	>	7	V	>7V		continuous		
		throttle blade	throttle blade		change		change	battery voltage		,	v	>1 V		continuous		
	P2107	amplifier	amplification value	<	3.9961	V	<3.9961V	vehicle speed	<=	0	mph	<=0mph	< 6 sec	0.01 sec	immediate	immediate
		adjustment of	·													
		throttle position	or					engine speed	<	40	rpm	<40rpm		once per throttleAdaption		
			amplification value	>	4.3242	V	>4.3242V	engine coolant	>=	5.25	° C	>=5.25° C				
			or					temperature engine coolant	<=	84.75	°C	<=84.75° C				
			OI					temperature	<=	64.75	C	<=64.75 C				
			offset value	<	-0.1501	V	<-0.1501V	intake air	>=	5.25	° C	>=5.25° C				
			or					temperature intake air	<=	60	° C	<=60° C				
								temperature								
			offset value	>	0.1501	V	>0.1501V	battery voltage accelerator pedal	> <	9.99 14.9	V %	>9.99V <14.9%				
								position		14.5	76	<14.976				
	P2119	functionality of	throttle blade return	>	0.56	sec	>0.56sec	vehicle speed	<=	0	mph	<=0mph	0.56 sec	0.01 sec	immediate	immediate
		return spring	response					engine speed	<	40	rpm	<40rpm		at key on		
								engine coolant	>=	5.25	° C	>=5.25° C	once	at noy on		
								temperature engine coolant		84.75	° C	<=84.75° C	per			
								temperature	<=	04./0	C	<=04.75° U	per			
								intake air	>=	5.25	° C	>=5.25° C	ignition			
			+					temperature intake air	<=	60	° C	<=60° C	on			
								temperature	-				J			
						·		battery voltage	>	9.99	V	>9.99V				

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
								accelerator pedal position	<	14.9	%	<14.9%				
Electronic Throttle																
	P2176	throttle exchange detection	range check poti1 value at lower stop					vehicle speed	<=	0	mph	<=0mph	1 sec	0.01 sec	immediate	immediate
		learn fail	throttle potentiometer 1 voltage	<	0.212	V	<0.212V	engine speed	<	40	rpm	<40rpm		at key on		
		or	or					engine coolant temperature	>=	5.25	° C	>=5.25° C	once			
		initial throttle learn failed	potentiometer 1	>	0.865	V	>0.865V	engine coolant temperature	<=	84.75	°C	<=84.75° C	per			
		or	voltage					intake air temperature	>=	5.25	° C	>=5.25° C	ignition			
		learning prohibited due to	range check poti2 value at lower stop			0	0	intake air temperature	<=	60	°C	<=60° C	on			
		secondary parameters not	throttle potentiometer 2	<	4.14	V	<4.14V	battery voltage	>	9.99	V	>9.99V				
		met or	voltage or					accelerator pedal position	<	14.9	%	<14.9%				
		minimum throttle position	throttle potentiometer 2 voltage	>	4.84		>4.84									
		out of range														
Throttle Position	P0121		sensor difference	>	9	%	>9%	battery voltage	>	7	V	>7V	continuous	0.1 sec	0.4 sec	two driving
Sensor 1 (primary)	P0122	voltage plausibility to other poti	sensor circuit low voltage	<	0.176	V	<0.176V							continuous	continuous	cycles each
	P0123	poti	sensor circuit high voltage	>	4.629	V	>4.629V								or 4 sec	with: 0.4 sec
															cumulative	continuous
Sensor 2 (redundant)	P0221	range check poti voltage,	sensor difference	>	9	% V	>9%	battery voltage	>	7	V	>7V	continuous	0.1 sec		or 4 sec
	P0222 P0223	plausibility to other poti	voltage sensor circuit high	>	0.156 4.883	V	<0.156V >4.883V							continuous		cumulative
	. 0220		voltage			•	7 110001									
function monitoring of microcontroller	P0606	torque comparison	irreversible error of torque comparison	true			true						5.5 sec	continuous	0.2 sec	2 dcy
(PCM level 2 command check)																
			(current and maximum allowed engine													
			torque out of range)													

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
			comparison	true			true									
			(calculated and													
			measured engine													
			load out of range)													
			out of range)													
		engine speed	irreversible error of													
		comparison	engine speed													
			comparison	true			true									
			(calculated and													
			measured engine													
			speed													
			out of range)													
		accelerator pedal	irreversible error of													
		signal comparison	accelerator pedal													
			signal comparison	true			true									
			(synchronism													
			between the two													
			pedal sensors out of range)													
			or range)													
		monitoring of AD	irreversible error of													
		converter queue	AD-converter queue													
			monitoring	true			true									
			monitoring	liue			uue									
			(queue not running)													
		range check of	irreversible error of													
		lower mechanical	lower mechanical													
		throttle valve		true			true									
		position	throttle valve position limit check													
			position innit check													
			(position out of													
			range)													
		check of variant	irreversible error of													
		coding	variant coding													
		ocug	check	true			true									
			(coding is incorrect)													
		check of AD-	irreversible error of													
		converter signal	AD-converter signal													
		+	check	truc			true		-			-				
		+	GIEGN	true			uue		+			+				
		1	(converted low													
			voltage test impuls													
		-	out of roy				-		-			-				
			out of range)													

Code Straight Security and	Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
Marry Improve transport Improve transpor	System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
Management Man																	
			timing	comparison of	true			true									
Commonwealth Comm				ignition timing value	ilue			tiue									
Complement is worting Complement Complement is worting Complement																	
P000				complement is													
Compare land value of vertication Value are not vertication Value ve																	
and verification of the femology model expense desired. Marcian controller model expense desired about expense desired. And funding model expense desired to the expense desired about expense desired. And funding model expense desired about expense desired about the expense desired. And funding model expense desired about the				verification	true			true									
Marcino controller monitoring model Marcino controller monitoring model Marcino controller monitoring model Marcino controller monitoring model Marcino controller Marcino M																	
Represented Note Represented Represent																	
regions or drook has defected a fault or function from true from the following provided from the following provide			function controller	monitoring module													
Composition																	
Signal check activated service of the last					true			true									
Signal check activated service of the last			watchdog output	WDA signal	true			true									
Section of the continuity of t																	
Comment Comm			ayan alta aa	internal augusts	Avisa			47110									
P0605 rationality check wrong ROM checksum P0605 rationality check wrong ROM checksum P0605 rationality check wrong ROM checksum P0606 rationality check wrong cyclic ROM checksum P0606 rationality check wrong cyclic ROM checksum P0606 rationality check wrong cyclic ROM checksum P0607 rationality check wrong cyclic ROM checksum P0608 rationality check wrong cyclic ROM checksum P0609 rationality check wrong cyclic ROM checksum P0609 rationality check wrong cyclic ROM checksum P0609 rationality check wrong cyclic ROM checksum P0600 rationality check of RAM checksum P0600 rationality check wrong cyclic ROM read and write to rune rune P0600 rationality check wrong cyclic ROM read and write to rune rune P0600 rationality check wrong cyclic ROM read and write test of rune rune P0600 rationality check wrong cyclic ROM read and write test of rune ru					tiue			uue									
P0605 rationality check wrong ROM checksum P0605 rationality check wrong ROM checksum P0606 rationality check wrong ROM checksum P0606 rationality check wrong cyclic ROM checksum P0606 rationality check of RAM P0607 rationality check of RAM P0608 rationality check of RAM P0608 rationality check of RAM P0609 rationality check of RAM P0609 rationality check of RAM P0609 rationality check of RAM P0600 r																	
checksum checksum checksum checksum checksum checksum checksum checksum of che	ECM Monitoring																
Complety		P0605	rationality check -		true			true						30 sec	at key off	2.6 sec	immediataly
March Marc				1					driving cycle						once per		
checksum of checks			cnecksum							true			true		dcy		
checksum of checks																	
checksum Checks		P0605	rationality check -	wrong cyclic ROM checksum of	true			true						5 sec	0.04 sec	2.6 sec	immediataly
of RAM test failed of the last driving cycle completly once per completly of RAM writeability check of RAM write test of true true of RAM write test of true true of RAM test failed of RAM true of RA				1 critical regions											continous		
of RAM test failed of the last driving cycle completly once per completly of RAM writeability check of RAM write test of true true of RAM write test of true true of RAM test failed of RAM true of RA																	
Completivation Comp		P0604	writeability check of RAM	RAM read and write test failed	true			true	of the last					30 sec	-	2.6 sec	immediataly
P0604 writeability check cyclic RAM read and of RAM write test of true true true continous									completly								
of RAM write test of true true continous								-	finished	true			true		dcy		
true true continous		P0604												1 sec	0.04 sec	2.6 sec	immediataly
Critical regions tailed				critical regions failed	true			true							continous		

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P0606	rationality check -		true			true						0.05 sec	at key on	2.6 sec	immediataly
			shut down of power stages not possible													
		programming incomplete												once per		
														dcy		
	P0606	writeability check of Time Processing	TPU parameter RAM read and write	true			true						0.05 sec	at key on	2.6 sec	immediataly
		Unit (TPU) parameter RAM	test failed											once per		
														dcy		
	P0606	rationality check -	wrong TPU code RAM checksum	true			true						0.3 sec	0.1 sec	2.6 sec	immediataly
		verification of Time Processing												continous		
		Unit (TPU) code RAM checksum														
	P0606	rationality check -	difference between										0.3 sec	0.1 sec	2.6 sec	immediataly
			Time Processing Unit													Í
		time difference check	time and PCM time	>	0.001	sec	> 0.001 sec							continous		
accelerator		Voltage														
accelerator position sensor		accelerator position sensor														
position sensor	P 2123	range check high	accelerator position sensor voltage 1	>	4.824	V	> 4.824 V	for time	>	0.2	sec	> 0.2 sec	immediataly	continuously	0.2 sec	0.4 sec
								condition batterie voltage is sufficient for 5V accelerator sensor supply	true			true				
	P 2122	range check low	accelerator sensor voltage 1	<	0.898	V	< 0.898 V	for time	>	0.2	sec	> 0.2 sec				
			and accelerator	<	0.664	V	< 0.664 V									
			sensor voltage 2		0.004	v	V 0.004 V									
_			accelerator sensor voltage 1	<	0.898	V	< 0.898 V	for time	>	0.2	sec	> 0.2 sec				
			and													

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
			synchronization between voltages 1 and 2 violated (see values of absolute difference in accelerator sensor voltages depending on ranges in FP1P absolute difference check below)	true			true									
			and													
			error reaction accelerator-travel sensor limphome	false			false									
			and													
			high contact resistance at accelerator voltage 1	false			false									
	P 2138	absolute difference check	e absolute difference between both					condition lower limit voilated (see min fault path of FP1P)	false			false				
		fault time	accelerator sensor voltages in the range					condition lower limit voilated (see min fault path of FP2P)	false			false				
			below 1.25 V	>	0.215	V	> 0.215 V	error reaction accelerator-travel sensor limphome	false			false				
			or					condition batterie voltage is sufficient for 5V accelerator sensor supply	true			true				
			absolute difference between both													
			accelerator sensor voltages in the range													
			from 1.25 V to 3.496 V	>	0.273	V	> 0.273 V									
			or													
			absolute difference between both													
			accelerator sensor voltages in the range													
			above 3.496 V and	>	1.035	V	> 1.035 V									
			fullfilled for the time	>	0.24	sec	> 0.24 sec									

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
	P 2128	range check high	accelerator sensor voltage	>	4.824	V	> 4.824 V	for time	>	0.2	sec	> 0.2 sec				
		fault time	romage					condition batterie								
								voltage is sufficient for 5V accelerator	true			true				
								sensor supply								
	P 2127	range check low	accelerator sensor voltage 1	<	0.898	V	< 0.898 V	for time	>	0.2	sec	> 0.2 sec				
			and accelerator	<	0.684	V	< 0.684 V									
			sensor voltage 2 or													
			accelerator	<	0.684	V	< 0.684 V	for time	>	0.2	sec	> 0.2 sec				
			sensor voltage 2 and													
			synchronization between													
			potentiometers 1 and 2 violated													
			(see values of													
			absolute difference in													
			accelerator sensor	true			true									
			voltages depending on													
			ranges in													
			FP1P absolute difference check													
			below)													
			and													
			error reaction accelerator-travel	false			false									
			sensor limphome	idisc			idisc									
			and													
			high contact resistance at													
			accelerator voltage 2	false			false									
Diagnosis of CAN																
signal timeout –																
instrument panel	U0212	CAN signal missing	CAN message of Gateway ID 0x380/1	<	1.250	S	< 1.250 s	battery voltage	>	10	V	> 10 V		continuous	immediately	immediately
		9	received					hottonivoltoni		40	W	- 40 \/				
								battery voltage condition ignition	>	18 3	V s	< 18 V > 3 s	3 s			
								switch on for time CAN-Status	true			true				
								Enable normal	ude			uue				
								message transmission								
								แสกรกกรรเดก				1			1	

Component/	Fault	Monitor Strategy	Primary Malfunction	Threshold	Threshold	Threshold	Threshold	Secondary	Enable	Enable	Enable	Threshold	Time	Frequency	Criteria	MIL
System	Code	Description	Signal and Criteria	Logic	Value	Units	Conditions	Parameters	Logic	Value	Units	Conditions	Required	of Checks	for Code	Illum.
BD ISO-15765					l							1				
ommunication																
us	U0001	ISO-15765 Bus Error	Invalid Message Received	=	invalid		=invalid	CAN Bus	initialized			initialized	0.5 sec	0.01 sec	immediately	immediately
			or Dual Port Ram Hardware Error;	=	error		=error	consisting of:	and ready			and ready	0.01 sec	continuous		
			or No Communication / Bus Off	=	bus off		=bus off	ignition on for	>	3	sec	>3sec	0.03			
								battery voltage	>	10	V	>10V				
								battery voltage	<	18	V	<18V				
								normal bus communication	running	-	-	running				
	U0101	Communication with TCM	TCM Message Timeout	=	message		=message	Automatic Transmission	equipped	-	-	equipped	2.5 sec	0.01 sec	immediately	immediately
	U0402	-	or Invalid Message Content	=	missing,		=missing,	CAN Bus	initialized	-	-	initialized		continuous		
					delayed,		delayed,	consisting of:	and ready			and ready				
					or		or	ignition on for	>	3	sec	>3sec				
					invalid		invalid	battery voltage	>	10	V	>10V				
					content		content	battery voltage	<	18	V	<18V				
								normal bus	running	-	-	running				
								communication								
nd																